

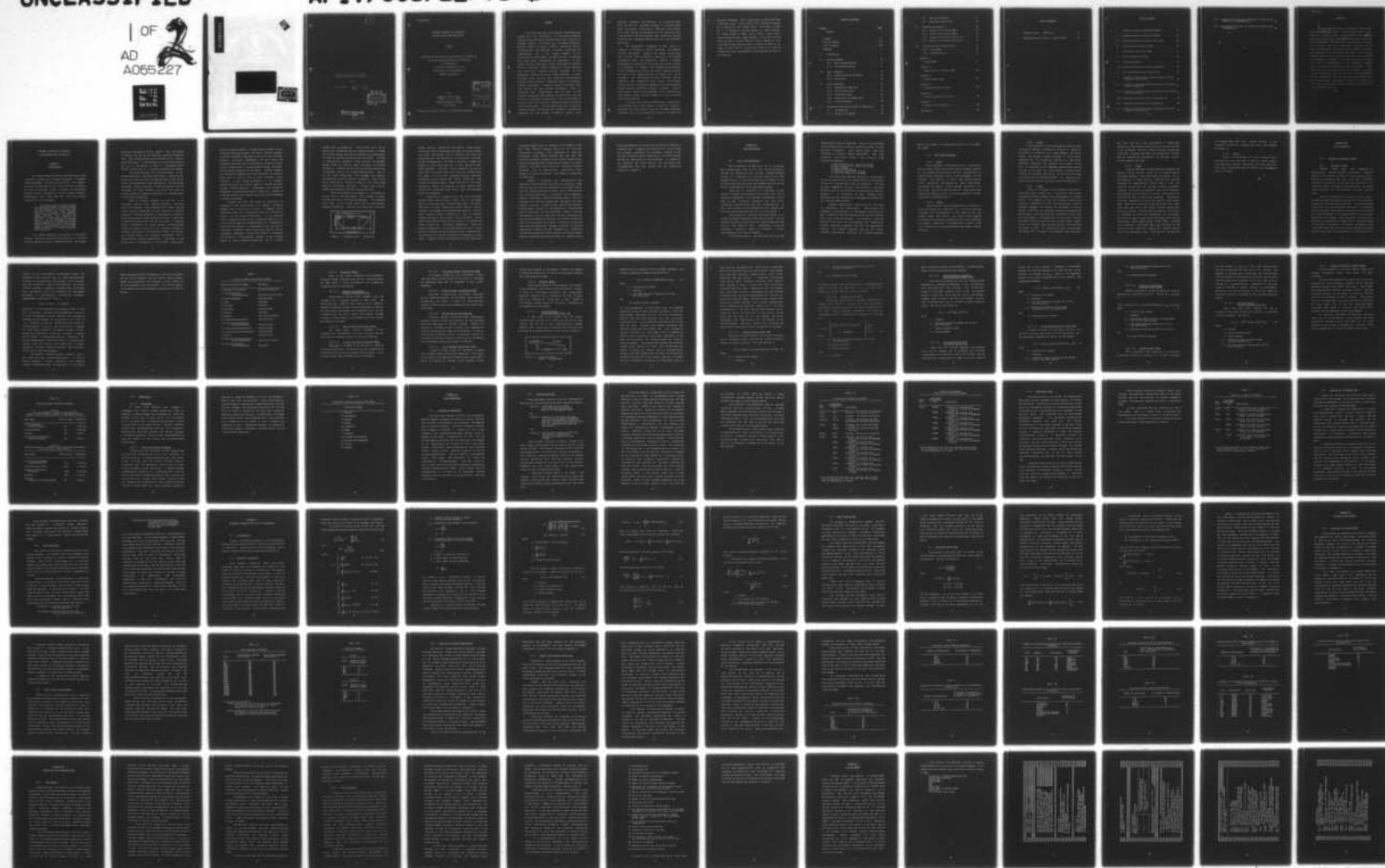
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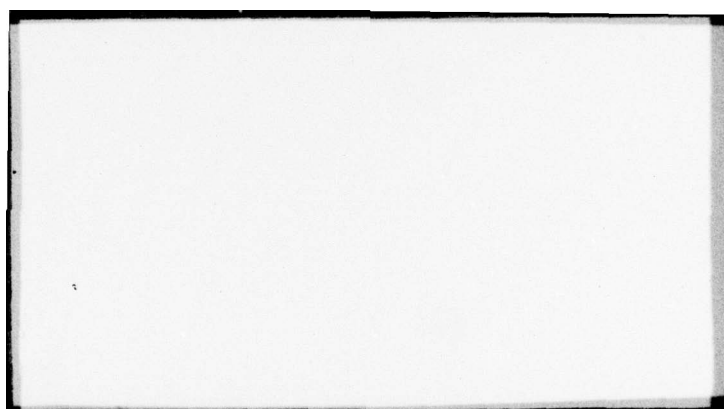
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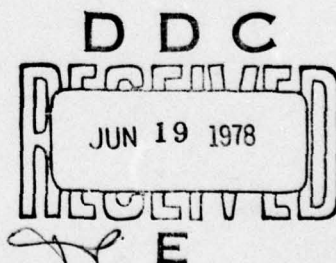
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SOFTWARE RELIABILITY: MODELLING  
TIME-TO-ERROR AND TIME-TO-FIX

THESIS

GCS/EE/78-2

Steve G. Castle  
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SOFTWARE RELIABILITY: MODELLING  
TIME-TO-ERROR AND TIME-TO-FIX

THESIS

Presented to the Faculty of the School of Engineering  
of the Air Force Institute of Technology  
Air University  
in Partial Fulfillment of the  
Requirements for the Degree of  
Master of Science

by

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Graduate Computer Science

March 1978

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## Preface

Over the past ten years Software Reliability has emerged as a new discipline. It has gained attention because of the vast amount of money being spent annually on computer software by private and governmental agencies. Numerous models to predict software reliability and its attributes have been presented by various individuals and organizations. One of the biggest setbacks in the verification of these models has been the lack of software error data bases. Recognizing the importance of this subject, Rome Air Development Center (RADC/ISIS) at Griffiss AFB, N.Y. contracted several companies to collect software error data from software projects developed for the government. RADC has now built a large repository of data. Utilizing files from the RADC repository, discrimination between several software reliability models by hypothesis testing is performed. A computer program is presented which will predict the best software reliability model for particular data. Time-to-error data was used in the software reliability model testing and time-to-fix data was used in the modelling of time-to-fix. Due to limitations of the data, some of the software reliability models considered could not be tested. For the models that could be tested, computer program subroutines were written to estimate the parameters of the software reliability models. After

parameter estimation was completed, the Likelihood Ratio Test was used for hypothesis testing to determine which model best suited the particular data base being tested. Also, model testing was implemented for the time-to-fix data using eleven of the more commonly used probability density functions, the Kolmogorov-Smirnov Test, and the Likelihood Ratio Test.

The theoretical foundation of this thesis is comprised of reliability theory, statistics, and computer software development. However, this thesis avoids going into too much detail concerning statistical and software reliability theory and formulation. Rather, a complete bibliography is provided for those desiring further details on development of formulas and mathematical techniques. With one exception the actual code of the computer programs and much of the output produced for thesis will not be presented. The contribution of these listings would be negligible when compared to their volume. The computer source code used in parameter estimation and discrimination between software reliability models is included. Usage of this program requires only knowledge of the difference in time between errors and the number of errors occurring during each interval.

A project such as this cannot be done without moral and technical support from others. I thank Dr. Thadeus L. Regulinski, my thesis advisor, for his invaluable guidance, assistance, and his willingness to share his academic and



technical knowledge. Also, I appreciate the assistance that I received from Dr. Paul Moranda of the McDonnell Douglas; Dr. E. Nelson, Mr. Tom Thayer, and Mr. Myron Lipow of TRW; Mr. H. E. Willman of Raytheon Company; my thesis sponsor, Mr. Allen Sukert of RADC; and my thesis readers, Capt. Edward Reeves and Capt. James Peterson. A day did not go by where my thesis did not effect my family, whether it be a late night at the computer center or asking for quiet in the house. I would like to give special thanks to my wife and children for their encouragement, understanding, and most of all patience.

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Abstract

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Various competing software reliability models were tested <sup>using</sup> ~~utilizing~~ time-to-error data extracted from a large data base provided by Rome Air Development Center, (RADC), Griffis Air Force Base, <sup>(N.Y.)</sup> New York. Only those models for which appropriate information was available from the RADC data base were used. Each model that was tested had its parameters estimated and discrimination between the models was performed by the Likelihood Ratio Test. Code for the computer program used in parameter estimation and Likelihood Ratio Testing is included. The same large data base was also used in determination of the probability density functions governing the random variable time-to-fix. Time-to-fix data was extracted from the data base and was sorted by error categories. Eleven of the more common probability density functions, along with the Kolmogorov-Smirnov Test and the Likelihood Ratio Test, were used to isolate the distribution that best modelled software time-to-fix for each particular data set.

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# SOFTWARE RELIABILITY: MODELLING TIME-TO-ERROR AND TIME-TO-FIX

## Chapter I Introduction

Each year billions of dollars are being spent on the contractual purchase and in-house development of computer software packages. The future does not look much brighter, especially considering that the cost of software is soaring. The cost of planning, coding, verifying and maintaining software has far exceeded the cost of computer hardware. Unfortunately, more often than not, the final software product is far too unreliable.

"The world's most carefully planned and generously funded software program was that developed for the Apollo series of lunar flights. The effort attracted some of the Nation's best computer programmers and involved two competing teams checking the software as thoroughly as the experts knew how to make it. In the aggregate about \$600 million was spent on software for the Apollo program. Yet, almost every major fault of the Apollo program, from false alarms to actual mishaps, was the direct result of errors in computer software (Ref [26]:52)."

This thesis addresses the problem of unreliable software. The first objective of the thesis is to test the numerous competing software reliability models. Many models

have been presented by various authors. Each has claimed his model to be the one that describes software reliability best. Most of these models were formulated on the basis of small data bases. A large software error data base provided for use in this thesis by Rome Air Development Center (RADC), Griffiss AFB, N. Y. permitted testing of the models.

The second objective is to determine which, if any, probability density functions (pdf) govern time-to-fix for entire error files and error categories within files. As far as can be determined no such analysis has been previously performed. Further discussion of these objectives will be enumerated in later chapters, but first the basics of reliable software, software reliability, and software time-to-fix must be understood.

What is reliable software and how can it be produced? This is a very important question. The first part of the question can be answered fairly simply and the answer can be agreed upon by the majority of software engineers. "Reliable software" is considered to be software that produces output within specified tolerance limits over a specified period of time. On the other hand, a "software error" is considered to be any software condition which causes the output to deviate from the specified tolerances. "Software reliability" is the probability that the software will perform within the specified requirements over a specified time interval (Ref[24]:5-2). The answer to the second part of the question is not so easily agreed upon.



There are several schools of thought being promoted on how to produce reliable software. One school believes strongly in better development techniques as the key to more reliable software. Structured programming, top down design and modularity are terms that are expounded by followers of this school. Another school proposes better testing and proof-of-correctness techniques as the answer. Computer hardware has long had the capability of fault tolerance, the state of being able to recover from an error condition. Fault tolerance is now being considered in the software engineering field as a viable means of obtaining reliable software (Ref[17]:230-232). Undoubtedly, each school of thought has something significant to offer and a manager of a software project must consider all options when purchasing or producing software.

Despite the best laid plans and procedures as promoted by the various schools of thought, a software package with no errors is a rarity. A program can be repeatedly tested, but "Testing only shows the presence of errors, not the absence (Ref[6]:33)". In the past the software manager has had no data to determine whether or not a new software system is reliable enough to be implemented, other than the instinct of a programmer or the assurance of a software contractor. How does he know that he has not purchased a nightmare? He has had no means of estimating the reliability of the software package. It was a simple matter to define software reliability, but it is quite

another thing to measure it. Even if there was a way to measure the reliability and the manager decided to accept the software system, how does he determine the mean-time-to-fix after the software system has been delivered? In order to ascertain the answers to these questions the software manager needs to know the basic principles of software reliability. Software reliability could someday easily play an important role in his decision making policy. But, it was not until recent years that attempts were made to mathematically describe software reliability. Some of the basic principles of software reliability are still being disputed by software engineers. A closer look into its history and background may help explain this fact.

Software reliability has emerged as a discipline of its own only in the past decade. Early attempts to model software were based on hardware principles. The "bathtub" curve (Fig. 1) is a model often used in demonstrating hardware reliability. The curve can be divided into three

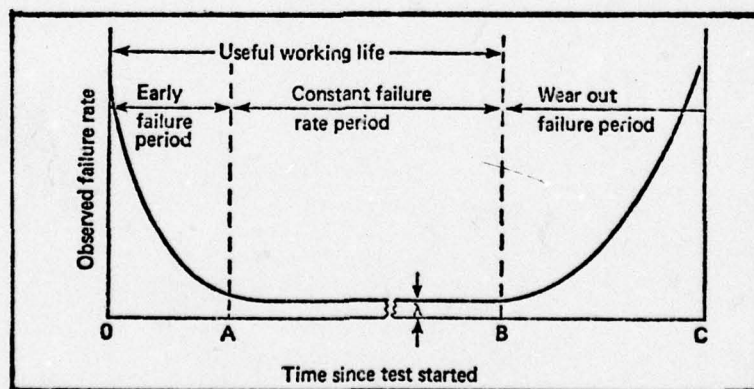


Figure 1. "Bathtub" Curve Ref([7]:3)



phases: burn-in, normal-life, and wearout. During burn-in the failure rate is decreasing with time; during the normal-life phase the failure rate is constant with time; and during wear-out the failure rate is increasing with time. As time increases over the life of a software package, the number of errors found per unit of time (detection rate) should decrease. This most closely resembles the burn-in phase. But, it has been shown in at least two projects that the number of new errors introduced during correction procedures is not trivial (Ref [7]:18, [24]:4-45). Some software reliability models assume there are no new errors introduced. Before any criticism is waged against these models, the environment under which they were developed should be recognized.

Collection of software errors and their attributes has only taken place in recent years. Many of the models had to be developed and validated using small data bases. There were no large software error data bases to use for analysis. This brings out an interesting question. From the large number of models available, how does the software manager know which one to choose for his project? Is one model better than all others for all data or are particular models suited for particular situations? These are questions that have to be answered before any faith can be placed in software reliability models. These questions will be answered in the process of meeting the objectives of this thesis. However, a large data base was required before any



reasonable answers could be obtained. In an attempt to get full value from its software dollar, the Air Force has established a software error repository at Rome Air Development Center (RADC), Griffiss AFB, New York. The repository presently consists of over 27,000 software error reports accumulated from at least seven different Air Force projects. Each error record within the repository contains attributes such as date-of-error, date-of-fix, error category, and error criticality. This thesis is based upon the above data.

Chapter 2 describes the characteristics and background of the different files from the repository. These files are the best that are available at the present time to test the software reliability models and to determine the pdfs governing time-to-fix for software error categories. Chapter 3 identifies software reliability models that were considered for testing purposes and delineates the model selection criteria. Details on the time-to-fix validation program, which was used in the selection of the governing pdfs of time-to-fix, are also presented. Chapter 4 includes information on how the data from the data repository was extracted and prepared for usage by the software reliability models and the time-to-fix program. Limitations of the data files are also pointed out. Chapter 5 outlines the program construction process that was necessary to validate and discriminate between the usable software reliability models. Chapter 6 summarizes the enormous amount of computer output

that was generated by this study and presents the results in condensed form. A summary is presented of the results from the parameter estimation and hypothesis testing of the software reliability models. Summaries of the distributions selected for time-to-fix are also presented. In support of the objectives set forth earlier, the conclusions and recommendations that were derived from the results are contained in Chapter 7.

## Chapter II

### Data Description

#### II.1 Basic Characteristics

Man's reluctance to admit error may be one reason why software error data has not been collected earlier. Besides, the computer has been the best scapegoat mankind has had in a long time. It's been too easy to say, "The computer did it." If the ever-rising cost of software is to be halted, man must admit that the mistakes were his and not those of some mythical, error-generating computer.

There was no precedence for collecting a large volume of software errors before, and the RADC files mark a significant beginning. Most assuredly, improvements can be made in data collection procedures, and each error-collecting contractor made many such recommendations. In fact a new, shorter, and more meaningful error category list has since been established (Ref [24]: 3-18 thru 3-20).

The selection of software reliability models to be tested was largely dependent on the data available. Not all software reliability models could be tested because the data did not lend itself to them. Consequently, before any discussion concerning models is presented, a basic understanding of the data is required.

As mentioned earlier, six data files from the RADC



repository were used as input data. The six files represent 27,000 software errors from five different projects by four different contractors. Each record within each file represents a Software Problem Report (SPR). With a few exceptions, each record within a file consists of the following information:

- 1) Date software error report was opened
- 2) Date software error report was closed
- 3) Error category
- 4) Degree of criticality
- 5) Test phase when error occurred
- 6) Module in which error occurred.

One of the most important aspects to realize about the data is that it was not collected solely for the purpose for which it is being used in this investigation. The data is being accepted as the best data available. The error categories used in the collection of this data are listed in Appendix F. It represents 20 major software error categories and 164 software error subcategories (Ref[24]:3-3 thru 3-8) and (Ref[7]:45-50).

Seperate subfiles were created from the RADC files for time-to-fix and time-to-error. Time-to-error was computed as the difference in time between two successive SPRs. Within each SPR, the date the error occurred and the date it was fixed was recorded. From these two dates the time-to-fix for each error was computed. The beginning of the test phase was considered "day one" for computational purposes. All subfiles beginning with an "EF" prefix represent time-to-error files and all subfiles beginning

with an "FF" prefix are time-to-fix files (e.g. EF1, EF4A, FF1, FF5G).

## II.2 File characteristics

### II.2.1 File1

File1 represents 4519 software errors collected by TRW on a large command and control software package (Project 3). The software was written by TRW and a subcontractor in JOVIAL/J4 and contained 115,346 source statements and 249 routines. The majority of errors were detected during formal testing over approximately an eight month period. The command and control software package was tested in a batch mode. The entire file was used for time-to-error and time-to-fix analysis and the files were called EF1 and FF1 respectively (Ref[24]:2-2,2-3).

### II.2.2 File2

File2 contains the operational data for Project 3, which was referred to in Section II.2.1. The error data was collected over approximately a nine month period. The records within this file do not contain error category information and therefore time-to-fix could not be extracted by category. There were 451 software error records in the file. Time-to-error data was extracted and called EF2 (Ref [24]:2-2).

### II.2.3 File3

File3 consists of records representing SPR data from a project by TRW and a subcontractor (Project 2). Again, it was written in JOVIAL/J4 for a large command and control system. The software package consisted of 96,931 source statements and 173 routines and operated in a batch mode. Originally there were 436 software error records in the file. It consisted of two independent modifications and the file had to be split into two autonomous subfiles before time-to-error analysis could begin. The time-to-error files thus formed were called EF3A and EF3B. For time-to-fix the entire file was used and was simply called FF3 (Ref [24]).

### II.2.4 File4

File4 is a collection of 2165 software errors from a real-time control system for a land-based radar system developed by Raytheon Company over approximately a 37 month period. The majority of the 109 software modules were written in JOVIAL/J3, with the remaining modules coded in assembly language. The project was developed in several builds. A build was an independent computer development and coding phase. Sufficient data was not recorded in the files and the necessary information was not available from the contractor on how to break out the file into builds. Again, it must be stressed that the data was not collected with this study in mind. The time-to-error data was extracted and called EF4. Two means of collecting time-to-fix data



were used. One used a 365 day calendar to compute the difference in time between when the error was found and when it was corrected. The file created from this process was called FF4A. Another file, FF4B, was created from fix data that was computed and recorded by the contractor using a workday calendar (Ref [29]).

#### II.2.5 File5

File5 was generated by Boeing Aerospace Company from Software Problem Reports (SPRs) on an avionic software development package. There were 2036 error reports over an approximately 27 month period. JOVIAL/JB was used and accounted for approximately 40,000 lines of code. The remaining 80,000 lines of code were written in assembly language. The project was developed using seven functions, each function being an entity of its own. Time-to-error was extracted for each of these seven functions. The time-to-error was computed by counting the number of days between SPRs. These seven files were called EF5A, EF5B, EF5C, EF5D, EF5E, EF5F, and EF5G. Also, Boeing computed time-to-error by using a formula that totalled the number of daily hours of equipment use since the beginning of the test phase. This data was used to extract the time between SPRs and the files EF5AH, EF5BH, EF5CH, EF5DH, EF5EH, EF5FH, and EF5GH were generated. Time-to-fix data was extracted for the entire file and called FF5. Boeing also computed time-to-fix by the hundredths of hour. This data was extracted and

was labeled FF5H (Ref [7]). Further details on the preparation of this file and the other files are presented in Chapter IV.

#### II.2.6 File6

File6 is a collection of 11,728 software errors collected over the years 1967 to 1971 for Project Apollo, the manned lunar landing. Regretfully, this data base could not be used, because the dates of software error occurrences were not recorded.



## Chapter III

### Model Selection

#### III.1 Software Reliability Models

##### III.1.1 Potential Models

Numerous models have been suggested to stochastically represent software reliability. Listed at the end of this section in Table II are the models and their respective references that were considered for possible inclusion in this study. By no means does the absence of a model from Table II indicate its relative value. The models listed are those for which adequate literature could be found.

Software reliability can be measured in two ways: reliability growth and interval reliability. The distinction between the two is extremely important. Reliability growth is just what its name indicates, the growth in reliability as time increases, where time is measured as starting on the first day of testing. It is expected that as time proceeds, more errors are removed, thus increasing the reliability. Ideally all errors should be found and a reliability equal to 1.00 would be achieved. For interval reliability, time is measured since the last error and the probability density function represents the distribution of time-to-error. An

interval is the time between two successive errors. The probability that an error will be found (unreliability) increases as the time since the previous error increases. Thus, the reliability is high in the beginning. But, as the software package or program is exposed longer and longer since the previous error, the probability of the package performing to specifications (reliability) decreases. Mathematically this can be stated by

$$R(x,T) = P[X(t) = 1, T \leq t \leq T+x]$$

where  $X(t) = 1$  if the software is operating at time "t" and  $X(t) = 0$  otherwise. Inherent in this formulation is that at "T", the starting point of the interval, the software is operating and the duration of the interval is "x" (Ref [1] : 8). Knowledge of interval reliability would enable the software manager to ask what the reliability of a package was after being exposed to "x" number of hours or days. Reliability growth would enable him to release a package when it reached a predetermined level of reliability. The uses and combinations of these two types of reliability are endless. But the crucial point being made is their difference, and that interval reliability and reliability growth are two different concepts.

The software reliability models listed in Table I were based upon many different principles. In order to produce meaningful results, testing of the competing software reliability models was narrowed to only include

those based upon interval reliability. With this constraint and the lack of adequate data for certain models, several models were eliminated from inclusion in this thesis, as will be discussed in the next section. For further details on the models that were eliminated, references are given in Table I.



Table I

Potential Software Reliability Models	
Software Reliability Model	Reference
1) Shooman's Exponential	Ref([22],[23],[27])
2) Jelinski-Moranda De-Eutrophication	Ref([8],[14],[15],[23])
3) Schick-Wolverton	Ref([30],[23])
4) Weiss	Ref([28])
5) Corcoran	Ref([3])
6) Markovian	Ref([23],[25])
7) Nelson	Ref([16])
8) Weibull	Ref([23],[20],[27])
9) Lipow-Schick-Wolverton	Ref([12],[23])
10) Lipow-Jelinski-Moranda De-Eutrophication	Ref([12],[23])
11) Modified-Schick-Wolverton	Ref([12],[23])
12) Reliabilty Growth Modelling	Ref([9],[23])
13) Mills	Ref([21],[9])
14) Jelinski-Moranda-Geometric De-Eutrophication	Ref([14],[15],[23])
15) Modified Geometric De-Eutrophication	Ref([23])

### III.1.2 Eliminated Models

Seven of the models considered were eliminated, primarily because necessary data was not contained within the RADC files. A brief discussion on the reasons for eliminating each is given below.

#### III.1.2.1 Shooman's Exponential Software Reliability Model

Unfortunately, several data elements were not available for a complete testing of this model. The processing rate, number of total hours in test, number of machine instructions, number of runs terminating in failure, and total time of successful and unsuccessful runs were not available from the files. Rather than making a biased estimate of these inputs, it was thought best not to include this model in the study.

#### III.1.2.2 Weiss Software Reliability Model

The Weiss model required knowledge of the probability of correcting an error and the test time for successes and failures, neither of which was available.

#### III.1.2.3 Corcoran Software Reliability Model

Knowledge of  $N$  number of trials with  $N_i$  number of failures and  $N_j$  number of successes and the probability of correction of the error was required for this model. As in the Weiss model, the information was not available.

#### III.1.2.4 Markovian Software Reliability Model

The primary reasons for the elimination of this model were that it did not fall into the scope of the study and sufficient time was not available to give a fair assessment.

#### III.1.2.5 Nelson Software Reliability Model

There was no control over the original test input for the modules from which the data bases were collected. Consequently, the number of inputs for which execution failures occurred could not be examined and this model could not be used.

#### III.1.2.6 Reliability Growth Modelling

As stated earlier, reliability growth modelling is concerned with the growth of reliability as time increases since the beginning of software testing. However, the majority of the models listed in Table I are dependent on interval reliability and model the distribution of time-to-error between successive errors. As mentioned earlier, it was deemed in the best interest of this study to investigate only those models based upon interval reliability.

#### III.1.2.7 Mills Software Reliability Model

A number of known errors can be seeded or tagged into a program, whose code has been completed. On the basis of the number of indigenous and induced errors found after a period of testing, an estimate can be computed for the



initial error content of the program. Seeding and tagging of software modules were not done for the projects involved, thus eliminating this model.

### III.1.3 Selected Models

Eight models remain for which adequate data exists. In the subsections that follow a brief description is given of each. For each model a detection rate is specified, where the detection rate is defined as the rate at which errors are detected for a given unit of time. Chapter V will present further details on the actual computation of the parameters for the models.

#### III.1.3.1 Jelinski-Moranda De-Eutrophication Model (JM)

In this model it is assumed that the initial detection rate is given by  $N\phi$ , where  $N$  is the initial error content, and  $\phi$  ( $\phi$ ) is the proportionality constant (Ref[14]: 327). As an error is removed, the detection rate decreases in a stepwise fashion as can be seen in Figure 2.

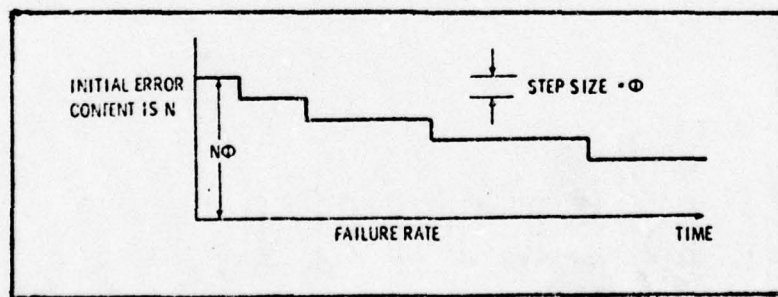


Figure 2. De-Eutrophication  
Process Ref([21]:482)

Between errors the detection rate is assumed constant. The resulting probability density function (pdf) is

$$f(t_i) = \phi[N-(i-1)]\text{EXP}\{-\phi[N-(i-1)]t_i\} \quad (1)$$

where

$N$  = initial error content

$i$  = interval

$t_i$  = the time separation between the  $(i-1)$ st  
and " $i$ "th error

and

$\phi$  = proportionality constant ,

Two basic assumptions of this model point out potential problems in using the RADC data with this model. First, the model assumes that there is only one error per interval. However, the data were collected such that errors were recorded by days. On any particular day there could be more than one error. Jelinski and Moranda recognized this conflict in data they used (Ref[8]: 475). They proposed to use each SPR date as a "stop date" and to disregard the number of errors occurring on this date. Regardless of how many errors occurred, the software system has failed to function properly. This approach was accepted for model JM. Another model based on JM takes into consideration the number of errors per interval and is discussed later. Secondly, the model assumes that each error is corrected and removed before the next error occurs. This was not always the case as revealed by the data in the RADC files, where an



error could be discovered, but other error(s) could have been found before the first one was corrected. This dilemma could have been caused by nonfatal errors, which do not completely halt the software. A remedy for this problem could not be found. Intervals could have been based on weeks instead of days, in hopes that most errors were corrected within the week. Inspection of the files showed that there still would be overlapping, and much valuable information would be lost by consolidating the errors. For some files the most common interval of time between "stop dates" would become one week. This produces problems when model parameters are estimated. Taking all of this into consideration, it was felt that the best approach was to retain the day as the basic unit of time and to use the model with the data as is, even though the errors overlapped. This approach does limit the validity of the results produced. Only with further error collection and actual model testing will the full implication be realized.

#### III.1.3.2 Schick-Wolverton Model (SW)

This model is quite similar to JM, but the detection rate is dependent on the time interval between successive errors, as well as N and phi. The resulting pdf is

$$f(t_i) = \phi[N-(i-1)]t_i \text{EXP}\{-(\phi/2)[N-(i-1)]t_i^2\} \quad (2)$$

where

N = initial error content

i = interval

$t_i$  = the time separation between the (i-1)st  
and the "i"th error

and

$\phi$  = proportionality constant

The input data were used as "stop dates", disregarding the number of errors at each stop. Also, the data were accepted, realizing that the errors do overlap.

### III.1.3.3 Weibull1 Model (WM1)

This model was applied to software reliability by Wagoner (Ref [27]:D-1). Wagoner used the least square method for estimating the scale and shape parameters, but for this thesis parameter estimation was performed differently as will be presented in Chapter V. The pdf is:

$$f(t_i) = \begin{cases} \alpha/\beta (t_i/\beta)^{\alpha-1} \text{EXP}[-(t_i/\beta)^{\alpha}] & \begin{cases} t_i \geq 0 \\ \beta > 0 \\ \alpha > 0 \end{cases} \\ 0 & \text{elsewhere} \end{cases} \quad (3)$$

where

$t_i$  = the time separation between the (i-1)st  
and "i"th error

$\beta$  = scale parameter

$\alpha$  = shape parameter

and

$i$  = interval

Again, inputs are treated as "stop dates", disregarding the number of errors occurring at each interval.

#### III.1.3.4 Jelinski-Moranda Geometric De-Eutrophication Model (JMG)

This model is similar to JM, but the detection rate decreases in a geometric progression on the occurrence of each individual error (Ref [14]:327). The initial error content is no longer fixed at N, as in JM. An infinite number of errors can occur over the life of the software package. Only one error can occur per interval of time, thus restricting the data to be used as "stop dates" as before. The pdf for this model is:

$$f(t_i) = Dk^{i-1} \text{EXP}(-Dk^{i-1}t_i) \quad (4)$$

where

i = interval

$t_i$  = the time separation between the (i-1)st and "i"th error

D = initial detection rate

k = ratio constant

#### III.1.3.5 Lipow-Jelinski-Moranda De-Eutrophication (LJM)

Lipow (Ref [12]:1-7) has suggested that numerous errors in an interval can be accounted for by making modifications to the detection rate of the JM model. The new detection rate incorporates the number of errors found up



through the (i-1)st interval. Throughout the parameter estimation process the quantity (i-1), that was used in the JM model, is replaced by  $(n_{i-1})$ , which is the cumulative number of errors found up through the (i-1)st interval. The resulting pdf becomes

$$f(t_i) = \phi(N-n_{i-1})\text{EXP}[-\phi(N-n_{i-1})t_i] \quad (5)$$

where

$N$  = initial error content

$i$  = interval

$t_i$  = the time separation between the (i-1)st and "i"th error

$n_{i-1}$  = cumulative number of errors found through the (i-1)th time interval

and

$\phi$  = proportionality constant

#### III.1.3.6 Lipow-Schick-Wolverton Model (LSW)

In order to account for any number of errors in an interval in the SW, Lipow (Ref [11]:1-7) modified the SW in the same manner suggested for the JM. The pdf becomes

$$f(t_i) = \phi(N-n_{i-1})t_i\text{EXP}[-(\phi/2)(N-n_{i-1})t_i^2] \quad (6)$$

where

$N$  = initial error content

$i$  = interval

$n_{i-1}$  = cumulative number of errors found through the (i-1)th time interval

$t_i$  = the time separation between the (i-1)st  
and "i"th error

and

$\phi$  = proportionality constant.

#### III.1.3.7 Modified Lipow-Schick- Wolverton Model (MLSW)

Another variation of SW and its detection rate was presented by Lipow (Ref [12]:1-7). The pdf for the model is:

$$f(t_i) = \phi(N-n_{i-1})[T_{i-1}+(t_i/2)]\text{EXP}\{-\phi(N-n_{i-1})[T_{i-1}+(t_i/2)]t_i\}$$

where (7)

$N$  = initial error content

$i$  = interval

$n_{i-1}$  = cumulative number of errors found through  
the (i-1)th time interval

$t_i$  = the time separation between the (i-1)st  
and "i"th error

$T_{i-1}$  = cumulative time through the (i-1)st error

and

$\phi$  = proportionality constant

#### III.1.3.8 Weibull2 Model (WM2)

WM2 is identical to WM1, except that it accounts for the number of errors in interval "i". In order to account

for the number of errors in each time interval, each interval is replicated for each error in the interval. For instance, an interval that was two days long and contained five errors would be represented by five data points, where each data point has an interval of two days. Each error is treated as a separate entity, independent of the other errors in the same or another interval, and represents a data point. The pdf is the same as Eq.(3), but there are many more data points considered in the parameter estimation process.

#### III.1.3.9 Modified Geometric De-Eutrophication Model (MG)

Sukert (Ref [23]: 19-21) modified the JMG by allowing for more than one error per interval. It was based on Lipow's formulas. The pdf is:

$$f(t_i) = D(k^{n_{i-1}}) \text{EXP}[-D(k^{n_{i-1}})t_i] \quad (8)$$

where

$i$  = interval

$D$  = initial detection rate

$k$  = ratio constant

$n_{i-1}$  = cumulative number of errors found  
through interval " $i-1$ "

$t_i$  = the time separation between the  $(i-1)$ st  
and " $i$ "th error



#### III.1.4 Software Reliability Model Summary

With the addition of the extra Weibull model, nine software reliability models were chosen for model validation.

The first four models only required " $t_i$ " and "i" for estimation of their parameters, treating " $t_i$ " as the time separation between "stop dates" (SPR dates). These models will henceforth be classified as Group I models. The last five models account for the number of errors per SPR date and will be classified as Group II models. They require " $t_i$ ", "i", and the number of errors occurring per SPR date. For these models, " $t_i$ " is the time separation between successive SPRs. Table II lists the nine models, their acronyms, and the parameters requiring estimation.

It should be noted that one additional model was found late in the development of this thesis, that could possibly be included in Group II of Table II. It is the Geometric Poisson Model by Moranda (Ref [14]:330). There was not enough time to include the model in this study.

Table II

## Selected Software Reliability Models

## Group I

Input Requirements - Length of each interval  
(number of days between each pair of successive errors)

Model name	Model acronym	Parameters
Jelinski-Moranda De-Eutrophication	JM	N and $\phi$
Schick-Wolverton	SW	N and $\phi$
Weibull1	WM1	$\alpha$ and $\beta$
Jelinski-Moranda-Geometric De-Eutrophication	JMG	D and k

## Group II

Input Requirements - Length of each interval and the number  
of errors within each interval

Model name	Model acronym	Parameters
Lipow-Jelinski-Moranda De-Eutrophication	LJM	N and $\phi$
Lipow-Schick-Wolverton	LSW	N and $\phi$
Modified-Lipow-Schick- Wolverton	MLSW	N and $\phi$
Weibull2	WM2	$\alpha$ and $\beta$
Modified Geometric De-Eutrophication	MG	D and k

## III.2 Time-to-Fix

### III.2.1 Background

If within each software error category or subcategory the random variable time-to-fix could be modelled, a software manager could determine the worst case estimate on how long it would take to fix a particular error. Of course, this is assuming that the type of error is known, which is not always the case. Ideally, a software manager could use established pdf's for error categories, determine the worst case estimate, and thereby, eliminate the haphazard guesswork, which so often underestimates fix time and results in cost overrun and strained working relationships.

### III.2.2 Time-To-Fix Program Selection

Time-to-fix is the difference in time between when the error was discovered and when it was corrected. It could be measured in central processing time, days, weeks, or any of various ways. The data in the RADC files was recorded by days. No information could be found on other previous attempts to model time-to-fix. A computer program (Program Model) written by T. L. Regulinski (Ref [18]) was used as the basis for determining the pdf that governed the time-to-fix data. Program Model accepts time-to-fix data and estimates the parameters for the probability density functions listed in Table III. After parameter estimation,



each pdf is tested for goodness of fit by the Kolmogorov-Smirnov Test (Ref [5],[10],[13]). Each distribution is either accepted or rejected at a significance level of 0.20. Of those accepted, the Likelihood Ratio Test (Ref [4] and [19]) is used to select the one that best models the particular time-to-fix data set. A modification to Program Model allowed a data file containing two or more different error categories to be sorted by error category and subsequently have a distribution selected for time-to-fix within each category. Henceforth, this new program will be called Program Time-To-Fix.

Table III

Time-To-Fix Density Functions (Ref [18])

---

Distribution Name

---

- 1) Uniform
- 2) Exponential
- 3) Weibull
- 4) Normal
- 5) Log-normal
- 6) Gamma
- 7) Logistic
- 8) Extreme Value-Largest
- 9) Extreme Value-Smallest
- 10) Pareto
- 11) Laplace

## Chapter IV

### Data Preparation

#### IV.1 Preparation Background

Six files were received from the RADC repository. Separate computer programs were written to extract the data from the RADC files because each contractor recorded the data in different formats. The files contained virtually every category in Appendix F. However, not all of the categories were considered legitimate software errors in respect to this study. Categories "L", "T", "U", "V", and "X" were deemed irrelevant for this study and were deleted as the time-to-error and time-to-fix files were being created. Respectively these categories are user requested changes, operator errors, questions, hardware errors, and non-reproducible errors. None of these are true software errors, even though they definitely do impact the development of a software package. Also, many records in File1, File2, File3 and File4 were classified as explanatory software problem reports (SPRs). These records were not representative of an error in the executable code and therefore, were not included in the time-to-error and time-to-fix files.



## IV.2 Time-To-Error Data

Three approaches could be taken for extraction of time-to-error data for the nine software reliability models.

Option 1) Treat each file as a whole  
and extract the time-to-error  
data in a chronological order.

OR

Option 2) Determine if the files were made  
up of separate software development  
entities, independent of others in  
the file, and then create time-to-error  
data in a chronological order for  
each subfile.

OR

Option 3) Isolate every program in each file  
and create a chronological  
time-to-error subfile for each  
program.

Option number three was discarded, because in a large system, any particular program may sit idle for a long period of time. Time between successive errors would be meaningless unless this idle time could be accounted for. Idle times for particular programs could not be obtained from the contractors. Also, much data could not be used, because many programs only had one or two errors recorded. Modelling with such a few number of data points would produce results of questionable value.

A compromise between Option 1 and Option 2 was required. File1, File2, and File4 could not be split into separate entities and were used in their entirety, with time-to-error being computed chronologically for the entire file.

File4 had numerous records which did not contain the date the error was found. As recommended by RADC and the contractor, each of these records arbitrarily had the date that the error was found set equal to the date that the error was fixed. Option 2 was used in the creation of subfiles for File3. During the creation of the software package from which the error data for File3 was collected, two independent software subprojects, called "modifications" by the contractor, were implemented. For each of these "modifications" a time-to-error file was created, each having its time-to-error computed independently from the other's. Similarly, File5 had to be split into seven different subfiles, each representing time-to-error data for a particular functional group of software. Each functional group was independently developed to fulfill a particular requirement for the master avionics system. Each group had its own software and a time schedule that was unique. All the files created thus far have had time-to-error computed as the difference in days between two consecutive errors. In addition, File5 contained time-to-error recorded and calculated by the contractor for the hourly equipment use time (Ref [7]:20). This data was split into seven separate subfiles, each containing time-to-error data for a specific functional group. A few records within four of these functions had the hourly data recorded incorrectly by the contractor. When the time between consecutive errors was computed it was not always a positive value. This could not

be possible. To correct these few records a linear interpolation estimate between the SPR dates was used to estimate the number of hours between errors.

Since File2 is the operational data for the same project as that used in the creation of File1, it seemed quite reasonable to track the entire project and to create a file which contained data from File1 (test data) and File2 (operational data). File2 was concatenated with File1 and the resulting file was then sorted by SPR date, thus creating error data for a continuing project.

Twenty time-to-error files resulted from the above procedures and are listed, along with a brief description, in Table IV. No mention was made of File6, because it did not contain data on when errors were found. File EF5C is given in its entirety in Appendix B as an example of the data created.



Table IV

## Time-To-Error Input File Table\*

RADC File	Extracted Time-To-Error File	Description
File1	EF1	Contains 152 records from File1
File2	EF2	Contains 86 records from File2
File1/2	EF1/2	Contains 238 records from the concatenation of File2 onto File1
File3	EF3A	Contains 54 records from MODA of File3
	EF3B	Contains 30 records from MODB of File3
File4	EF4	Contains 435 records from File4
File5	EF5A	Contains 149 records from build "A" of File5 as computed in days
	EF5B	Contains 146 records from build "B" of File5 as computed in days
	EF5C	Contains 51 records from build "C" of File5 as computed in days
	EF5D	Contains 83 records from build "D" of File5 as computed in days
	EF5E	Contains 92 records from build "E" of File5 as computed in days
	EF5F	Contains 102 records from build "F" of File5 as computed in days
	EF5G	Contains 80 records from build "G" of File5 as computed in days

\* All time-to-error files do not represent records with error categories "L", "T", "U", "V", and "X" or those that are explanatory in nature.

Table IV (Continued)  
Time-To-Error Input File Table\*

RADC File	Extracted Time-To-Error File	Description
File5	EF5AH	Contains 131 records from build "A" of File5 as computed in hours
	EF5BH	Contains 130 records from build "B" of File5 as computed in hours
	EF5CH	Contains 49 records from build "C" of File5 as computed in hours
	EF5DH	Contains 75 records from build "D" of File5 as computed in hours
	EF5EH	Contains 109 records from build "E" of File5 as computed in hours
	EF5FH	Contains 90 records from build "F" of File5 as computed in hours
	EF5GH	Contains 76 records from build "G" of File5 as computed in hours

\* All time-to-error files do not represent records with error categories "L", "T", "U", "V", and "X" or those that are explanatory in nature.

#### IV.3 Time-To-Fix Data

Splitting the files, as was done for time-to-error data files, was not necessary for the creation of time-to-fix data files. Time-to-fix is unlike time-to-error in that all of the information required for determining time-to-fix is recorded in one record and requires no knowledge of the previous record. Each contractor had his own software development techniques. For a particular contractor the techniques remained the same from one "build", "modification", or "functional grouping" to the next. Since the same techniques were used within any particular software project it appeared unnecessary to split the files by "modifications", "builds", or "functional groups" for creation of the time-to-fix data files. Combining all of the files into one large time-to-fix file would be quite unreasonable because each contractor developed his software using different techniques. Besides, one of the reasons for modelling time-to-fix was to see if there existed distributions which were the same from one project to the next.

A separate time-to-fix file for File1, File2, File3, File4, and File5 was created, and each record within the new files consisted of the number of days it took to fix the error and the error category from Appendix F. Any error found and fixed on the same day was considered to have a fix time of 0.5 days.



File4 also had time-to-fix computed using a work calendar. The difference between when the error was found and when the error was fixed did not include weekends or holidays. This data was extracted and used to create file FF4B.

In File5 additional data was available, so that a file (FF5H) could be created where time-to-fix was represented by the hundredths of hours to fix (Ref [7]:20).

Six files resulted from the above procedures and are listed along with a brief description in Table V.

Table V

## Time-To-Fix Input File Table\*

RADC File	Extracted Time-To-Fix File	Description
File1	FF1	Contains 2172 records from File1 using a 365 day calendar
File3	FF3	Contains 219 records from File3 using a 365 day calendar
File4	FF4A	Contains 1254 records from File4 using a 365 day calendar
	FF4B	Contains 1254 records from File4 using a workday calendar
File5	FF5	Contains 1603 records from File5 using a 365 day calendar
	FF5H	Contains 1603 records from File5 as recorded in hundredths of the hour

\* All time-to-fix files do not represent records with error categories "L", "T", "U", "V", and "X" or those that are explanatory in nature.

#### IV.4     Computation of Elapsed Time

Except for the error and fix files that have a suffix of "H", the calendar day is the basic unit of time. Each SPR is represented by a record and within each record all dates were recorded by month/day/year.

A seven year calendar was established to convert each month/day/year entry in a record into the number of days since 1 January 1970. The date 1 January 1970 was selected because it preceeded the earliest SPR and computations could be easily made using it. Once each time-to-error or time-to-fix date was transformed into the number of days since 1 January 1970, the number of days between the time-to-error or time-to-fix occurrences were easily calculated by subtracting the latest date from the earliest date.

A possible legitimate criticism of using the day as the unit of measure would be if the software package sat idle a lot or consisted of one program which was used sporadically. But on a large system, which is in continuous use, the day may be an appropriate unit of measure. CPU time has been suggested as an alternative. In the actual operation of a large computer system or a real-time system, it is sometimes difficult to track CPU utilization accurately. Data were not recorded in CPU time for the RADC files, but in future error collection efforts CPU time will undoubtedly be collected.



Four different contractors built the files and each file was recorded in a different format. Therefore, numerous computer programs were written to delete, extract, sort, and merge the records into identical formats which were usable by a time-to-error program and time-to-fix program.

#### IV.5 File Limitations

The creation of the files in Table IV was not a "cut and dry" decision. For instance, File4 was collected from a project which consisted of several independent software "builds". Each "build" was developed on a unique time schedule and ideally each "build" should have its own time-to-error subfile, but adequate information was not available in the file or from the contractor to permit segregation by "build".

The start date had to be determined for each time-to-error file. For files EF1, EF2, EF1/2, and a few of the subfiles in File5 the actual date at which formal testing began was specified in the contractor's reports. On other files an official date at which formal testing began ("day one") could not be obtained. Only the detection date of the first error was given in these cases. A date had to be established and three alternatives seemed most logical:

Alternative 1) Use the date of the first  
SPR as "day one"

Alternative 2) Use the date of the first  
SPR minus one day as "day one"

Alternative 3) Plot the data points and fit a straight line to the points. Project this line backwards to a date that would correspond to "day one".

Any of the three alternatives would be an approximation of the true "day one". If a software package is being tested thoroughly it is not unlikely that the first error will be found within the first day of testing. Therefore, "day one" was computed using Alternative 2 for those files requiring estimation of "day one". Declaring the date of the first SPR as "day one" as done in Alternative 1 would lose valuable data on the first SPR. Actual usage of Alternative 3 projected "day one" back to a date which was unacceptable. It was felt that the data from the first SPR was too important, especially for those models requiring the total number of errors per interval, to be lost by using Alternative 1 and Alternative 3 gave unreasonable predictions of "day one". Alternative 1 was tried for several files resulting in estimated parameters that were only slightly different by no more than a magnitude of one and distributions that were the same as for those using Alternative 2.

## Chapter V

### Parameter Estimation and Test of Hypothesis

#### V.1 Introduction

A means of parameter estimation and discrimination between the nine selected software reliability models had to be established. These functions were incorporated into a computer program called Program SRMOD (See Appendix A).

#### V.2 Parameter Estimation

Each software reliability model has certain parameters that must be estimated (See Table II). The models in Group I of Table II required only the time-to-error ( $t_i$ ) data from the data base, while those in Group II required time-to-error and the total number of errors per interval from the data base. Both of these inputs were available from the RADC files. From the extracted raw data, which consisted only of the time between successive SPRs and the number of errors within the interval, numerous calculations had to be made before parameter estimation could proceed. The cumulative number of errors up through each interval, the cumulative time up through each interval, the total number of time intervals, and the total number of errors had to be computed. Various other summations were



necessary before parameter estimation could be completed. These summations can be found in the equations that follow.

To estimate N and phi for the JM, SW, LJM, LSW, and MLSW models the following formulas (Ref [12]:2-3) were used:

$$\frac{K}{\hat{N}+1-(B/A)} = \sum_{i=1}^J \frac{M_i}{\hat{N}-n_{i-1}} \quad (9)$$

and

$$\hat{\phi} = \frac{(K/A)}{\hat{N}+1-(B/A)} \quad (10)$$

where

$$A = \begin{cases} \sum_{i=1}^J t_i & \text{for JM and LJM} \\ \sum_{i=1}^J (t_i^2/2) & \text{for SW and LSW} \\ \sum_{i=1}^J (t_i (T_{i-1} + t_i/2)) & \text{for MLSW} \end{cases}$$

$$B = \begin{cases} \sum_{i=1}^J i t_i & \text{for JM} \\ \sum_{i=1}^J (n_{i-1} + 1) t_i & \text{for LJM} \\ \sum_{i=1}^J (i t_i^2/2) & \text{for SW} \\ \sum_{i=1}^J (n_{i-1} + 1) (t_i^2/2) & \text{for LSW} \\ \sum_{i=1}^J (n_{i-1} + 1) t_i (T_{i-1} + t_i/2) & \text{for MLSW} \end{cases}$$

$t_i$  = length of time interval in which  
" $M_i$ " errors were observed

$T_{i-1}$  = cumulative time through (i-1)st interval

$$T_{i-1} = \sum_{r=1}^{i-1} t_r$$

$$T_0 = 0$$

$n_{i-1}$  = cumulative number of errors observed  
up through the (i-1)st time interval

$$n_{i-1} = \sum_{r=1}^{i-1} M_r$$

$$n_0 = 0$$

$M_i$  = number of errors in interval "i"

$j$  = total number of time intervals

$K$  = total number of errors observed

$$K = \sum_{i=1}^j M_i$$

The formulas are a consolidated version of several equations, each used to estimate  $N$  and  $\phi$  for a particular model, utilizing the maximum likelihood function. They are basically the same as stated by Lipow (Ref [11]:2-3) with the exception that equations 9 and 10 also consider estimation of parameters for models JM, SW, and LSW. In all cases the maximum likelihood estimate for  $N$  and  $\phi$  were used as explained in (Ref [8],[11],[14],[15],[23]).

Estimation of  $\alpha$  and  $\beta$  for WM1 and WM2 used formulas taken from Program Model (Ref [18] and [20]).

$$\hat{a} = \sqrt{\left[ \frac{S}{J-1} - \frac{R^2}{J(J-1)} \right]} * .6079271 \quad (11)$$

$$\hat{\beta} = \text{EXP}(R/J + .5772/\hat{a}) \quad (12)$$

where

$j$  = total number of time intervals

$$R = \sum_{i=1}^j \log(t_i)$$

$$S = \sum_{i=1}^j \log(t_i^2)$$

$t_i$  = length of time interval

The two geometric models, JMG and MG, required "D" and "k" to be estimated. Given that the pdf for the JMG is

$$f(t_i) = Dk^{i-1} \text{EXP}(-Dk^{i-1}t_i) \quad (13)$$

where

$i$  = interval

$t_i$  = length of time interval

$D$  = initial detection rate

$k$  = ratio constant

the maximum likelihood estimates for "D" and "k" can be determined (Ref [14]:330) and (Ref [11]:1). If given a sample of time-to-errors ( $t_1, t_2, \dots, t_j$ ) the likelihood function, denoted by "L", would be



$$L(t_1, t_2, \dots, t_j) = \prod_{i=1}^j D k^{i-1} \text{EXP}(-D k^{i-1} t_i) \quad (14)$$

where "j" equals the number of intervals. Taking the natural logarithm of both sides of equation (14) produces

$$\log L = [j \log D] + \left[ \sum_{i=1}^j (i-1) \log k \right] - \left[ \sum_{i=1}^j D k^{i-1} t_i \right] \quad (15)$$

Maximizing equation (15) with respect to "D" yields

$$\frac{\delta \log L}{\delta D} = \frac{j}{D} - \sum_{i=1}^j k^{i-1} t_i = 0 \quad (16)$$

and maximizing with respect to "k" yields

$$\frac{\delta \log L}{\delta k} = \left[ \frac{1}{k} \right] \sum_{i=1}^j (i-1) - D \sum_{i=1}^j (i-1) k^{i-2} t_i = 0 \quad (17)$$

The solution of equation (16) for "D" can then be substituted into equation (17) to arrive at

$$\frac{\sum_{i=1}^j i k^i t_i}{\sum_{i=1}^j k^i t_i} = \frac{j+1}{2} \quad (18)$$

Since "j" and the  $t_i$ 's are known quantities, equation (18) can be solved for "k". The solution will be called " $\hat{k}$ " and will be a maximum likelihood estimate for "k". Likewise, the " $\hat{k}$ " can be substituted into equation (16) to form

$$\hat{D} = \frac{j}{\sum_{i=1}^j \hat{k}^{i-1} t_i} \quad (19)$$

from which a maximum likelihood estimate for "D" can be derived.

Similarly the maximum likelihood estimates of "k" and "D" for MG were derived to yield

$$\frac{\sum_{i=1}^j n_{i-1} \sum_{i=1}^j k^{n_{i-1}} t_i}{j} = \sum_{i=1}^j (n_{i-1}) k^{n_{i-1}} t_i \quad (20)$$

$$\hat{D} = \frac{j}{\sum_{i=1}^j \hat{k}^{n_{i-1}} t_i} \quad (21)$$

where

i = interval

j = total number of time intervals

$n_{i-1}$  = cumulative number of errors up through the (i-1)st time interval

### V.3 Model Restrictions

One problem, as recognized by Lapadula (Ref [9]) and Sukert (Ref [23]), did arise in all models requiring an estimation of "N". To solve equation (9) for "N" (estimate for the initial error content), incremental values were substituted for "N" until a value was found that would make the left side of equation (9) equal to its right side.

For several data sets Program SRMOD aborted because the computer time spent trying to find such an equality exceeded the allowable execution time permitted on the processing computer. In all cases the estimate for "N" at the time of abortion was far greater than would be expected. If it is assumed the models are valid, then the software projects from which the data came from would have had serious problems. No information could be found that would indicate this fact. No positive reason could be found that would explain why some data files had this problem and others not.

Sukert (Ref [23]:41) suggested that it could be caused by short time intervals consisting of many errors at the end of a file. This pattern was prevalent in those files which had the problem in this study.

The simplest and most convenient means found to alleviate this problem, so that testing could proceed without being aborted, was to allow "N" (the estimate for the initial error content of the software package) to reach



n (the actual number of errors found thus far in the software package) plus 10,000. At this point it was deemed highly unlikely that a reasonable solution for "N" could be determined. When this situation occurred, "N" was set to this arbitrarily large sum. After all restrictions were resolved and the parameters were estimated for the models, a test of hypothesis was selected to discriminate between the models.

#### V.4 Likelihood Ratio Test

The Likelihood Ratio Test (LRT) was chosen as the easiest means of discriminating between the nine different distributions. The LRT is defined by

$$L(T) = \frac{f_1(t|H_1)}{f_0(t|H_0)} \quad (22)$$

where

$$f_r(T|H_r) = \prod_{i=1}^j f_r(t_i|H_r)$$

$$H_0: G(t) = F_0(t|\theta_0)$$

$$H_1: G(t) = F_1(t|\theta_1)$$

The null hypothesis,  $H_0$ , is that the sample of  $t_i$ 's taken from a population with an unknown cumulative distribution function,  $G(t)$ , is equal to a theoretical distribution,  $F_0(t|\theta_0)$ , where  $\theta_0$  is the known parameter(s) of "F". The

null hypothesis can be tested against the alternative hypothesis, which states that  $G(t)$  equals another theoretical distribution,  $F_1(t|\theta_1)$ . Given that the  $t_i$ 's are statistically independent then the quantity  $f_r(T|H_r)$  equals the joint pdf of the  $t_i$ 's. The criterion against which  $L(T)$  is measured for acceptance or rejection of a given hypothesis is called the threshold of the test and is denoted by " $\eta$ ". The threshold is determined by the cost of making a correct or incorrect decision based upon apriori probabilities of the hypotheses in question. For this application it was assumed that the distributions under test had equal likelihood of occurrence and that the cost for an incorrect decision, regardless of the decision, was the same. Also, it was assumed there was no penalty for a correct decision. Given these assumptions " $\eta$ " equals one and the LRT can be written

$$L(T) \begin{matrix} >H_1 \\ <H_0 \end{matrix} \eta \text{ or further } \ln[L(T)] \begin{matrix} >H_1 \\ <H_0 \end{matrix} \ln(1.) \quad (23)$$

which states that if the log of  $L(T)$  is less than the log of one, choose  $H_0$ , if it is greater than the log of one, choose  $H_1$ . The computational algorithm utilized in Program SRMOD was based on

$$\sum_{i=1}^j \{\ln[f_1(t_i|H_1)]\} - \sum_{i=1}^j \{\ln[f_0(t_i|H_0)]\} \begin{matrix} >H_1 \\ <H_0 \end{matrix} 0 \quad (24)$$

This approach can be repetitively applied to test several hypothesis against one another. Eventually, one hypothesis will be selected over all others. As an example, two models from Group II are tested against each other using EF1 as the sample population. The hypotheses are

$H_0$  : Distribution is the Modified Geometric Model

$H_1$  : Distribution is the Lipow-Schick Wolverton Model

Using the log of the maximum likelihood function as given in Appendix C for EF1, then

$$\sum_{i=1}^j \ln[f_0(t_i | H_0)] = -189.87$$

and

$$\sum_{i=1}^j \ln[f_1(t_i | H_1)] = -3937.13$$

which yields

$$\begin{array}{ccc} & >H_1 & \\ & 0 & \\ (-3937.13) - (-189.87) & & (25) \\ & <H_0 & \end{array}$$

or

$$\begin{array}{ccc} & >H_1 & \\ & 0 & \\ -3747.26 & & (26) \\ & <H_0 & \end{array}$$

Since -3747.26 is less than 0.0,  $H_0$  is selected over  $H_1$ . This process is continued with the other models until one emerges over all others.



However, a decision had to be made on whether or not all of the models could be tested against one another. It was quite obvious that the JM model, which required only time-to-error as input, could not be tested against the LJM, which required time-to-error and the number of errors per interval as input. The only reasonable answer to be found was that hypothesis testing would be dependent on input. Thus, JM, SW, JMG, and WM1, which required only time-to-error as input, were tested using the Likelihood Ratio Test. In a separate and independent test the LJM, LSW, MLSW, MG and WM2 models were tested using the Likelihood Ratio Test. For ease of computation the natural logarithm was used in computing the maximum likelihood function for each distribution. On all Program SRMOD's outputs the natural log of the maximum likelihood functions (LLR) is given. In several cases the maximum likelihood function became so small it was considered equal to zero by the computer. The logarithm of zero cannot be taken and Program SRMOD aborted. To resolve this problem the log of the maximum likelihood function was set arbitrarily to -99999.0 whenever the computer considered the maximum likelihood function equal to zero. On all of Program SRMOD's outputs an LLR equal to -99999.0 should be treated as an extremely large negative number greater than the natural logarithm of  $(\text{EXP}(-675.))$ . A complete listing of Program SRMOD is given in Appendix A.

## Chapter VI

### Execution And Results

#### VI.1 Execution of Program SRMOD

Program SRMOD was designed and developed to estimate the parameters for each of the software reliability models in Table II and then discriminate between the models by hypothesis testing. For each of the time-to-error files listed in Table IV, parameters were estimated by Program SRMOD for all of the software reliability models being considered. Next Program SRMOD did a hypothesis test using the Likelihood Ratio Test as described in Section V.4. Upon completion, a listing was printed containing the vital statistics. A complete self-documented copy of Program SRMOD is contained in Appendix A.

Data input requirements for Program SRMOD were fairly simple. Each input record represented the time between two successive SPRs and the number of errors that occurred within this time frame. From this data all calculations for parameter estimation and hypothesis testing could be made for both Group I and Group II models. Calculations for Group I models ignored the data field which contained the number of errors per time interval. EF5C is listed in its entirety in Appendix B as a sample of the input required.

A separate computer output listing was created for each group for a particular time-to-error file. In all there were 20 Group I output listings and 20 Group II output listings. Each listing was basically of the same format and contained information such as the total number of errors to date, total number of intervals, estimated parameters for each model, the log of the maximum likelihood function for each function, and finally the model selected by hypothesis testing. Appendix C contains all 40 output listings.

A summary of the results from Program SRMOD are presented in Tables VI and VII. The following section will discuss these results.

#### VI.2 Results from Program SRMOD

Table VI lists the time-to-error files, along with the software reliability models that were selected for each. Most obvious in Table VI is the number of files which had a geometric model selected for their time-to-error data. In Table VII it can be seen that the majority of files had a geometric model selected. EF1 was one of the largest time-to-error files and was extracted from File1. It contained data from 152 SPRs. The Schick-Wolverton Model was selected as the distribution which best modelled its time-to-error data points. However, when EF2 the operational data for the same software project, was joined with EF1, the Jelinski-Moranda Geometric Model was selected. The data for both



"modifications" (EF3A and EF3B) of File3 had the Jelinski-Moranda Geometric Model selected. EF4, which consisted of 149 data points from File4, had the Jelinski-Moranda De-Eutrophication Model selected for its distribution. File5 was divided into two groups of seven files. One group depicted data collected by the day, the other depicted data collected by the hour. Each of the seven files contained data from an independent functional group of software. The files for functional groups "A" and "D" (EF5A,EF5AH,EF5D,EF5DH) were the only files which had a different model selected for data collected by the day than for data collected by the hour. The Jelinski-Moranda Geometric model was selected the majority of the time for the subfiles of File5. In total three different models were chosen from Group I for the twenty files.

Group II was more consistent in its model selection. EF5GH was the only file that did not have the Modified Geometric Model selected for its time-to-error data. The Weibull2 model was selected for EF5GH. The data within EF5GH was data recorded by the hour for "functional group" "G" of File5. No obvious differences between this data and data in other files could be found.

Table VI

## Model Selection By Group\*

File	Distribution Selected From Group I	Distribution Selected From Group II
EF1	SW	MG
EF2	JMG	MG
EF1/2	JMG	MG
EF3A	JMG	MG
EF3B	JMG	MG
EF4	JM	MG
EF5A	JM	MG
EF5B	JMG	MG
EF5C	JMG	MG
EF5D	JM	MG
EF5E	JMG	MG
EF5F	JMG	MG
EF5G	JMG	MG
EF5AH	SW	MG
EF5BH	JMG	MG
EF5CH	JMG	MG
EF5DH	JMG	MG
EF5EH	JMG	MG
EF5FH	JMG	MG
EF5GH	JMG	WM2

\* As specified in Table V:

Group I consisted of the JM, SW, WM1, and JMG models and required only the difference in time between "stop dates" as input.

Group II consisted of the LJM, LSW, MLSW, WM2, and MG models and required time-to-error and the number of errors within each interval

Table VII

Selection Summary

Group I

Model	Number of files selecting model
-------	------------------------------------

JM	3
SW	2
WM1	0
JMG	15

Group II

Model	Number of files selecting model
-------	------------------------------------

LJM	0
LSW	0
MLSW	0
WM2	1
MG	19



### VI.3 Execution of Program Time-To-Fix

The data for Program Time-To-Fix was used in three different variations. First, each file in Table V was used as a continuous file to see if a distribution could be found for the random variable time-to-fix of an entire file. Next, an attempt to model time-to-fix within the major error categories (e.g. "AA", "BB", etc.) for a given file was performed. Finally, time-to-fix within subcategories (e.g. "AA010", "DD010", etc.) was modelled, trying to determine a distribution which best suited the data points in each subcategory of each file. There were 20 categories and over 140 subcategories whose time-to-fix data points were considered for modelling on each file in Table V. This means there were 160 output listings for each file or in total 960 listings from Program Time-To-Fix. This was too voluminous to include in this report. It was necessary to condense the output and include the results in table format, as can be seen in Tables VIII through XVII. Sample outputs from Program Time-To-Fix are given in Appendix D.

Each output listing consisted of four parts. First the estimates for the parameters were listed for the eleven distributions listed in Table III. Next the results from the Kolmogorov-Smirnoff test were printed. The Likelihood Ratio Test results followed and then finally the decision of which model, if any, was printed.

Input for Program Time-To-Fix consisted only of the

time-to-fix and the error category for that particular problem. As an example of the input required for Program Time-To-Fix a portion of FF1 is listed in Appendix E.

#### VI.4 Results from Program Time-To-Fix

Time-to-fix, without regard to an error category, could not be modelled at the 0.20 significance level for the given files. The Kolmogorov-Smirnoff test rejected all distributions when the files were used as a whole. No other significance levels were tried, primarily because of the time constraints of this study.

However, when the major error categories were extracted from the files and the time-to-fix data points for each category were modelled, distributions were selected. For example, there were 109 category "AA" errors in file FF5B and the Program Time-To-Fix selected the log-normal distribution as the distribution that best modelled time-to-fix for this error category. However, there were several categories for which time-to-fix could not be modelled. There were 192 category "AA" errors within file FF1, but no distribution was selected.

Table VIII reflects the percentage of categories which had distributions selected for their time-to-fix data. As can be seen, there was a wide difference between files. Categories "HH", "II", "KK", "PP", "RR", and "SS" had distributions selected for all six files. Time-to-fix for



some categories could not be modelled because there was either zero or only one data point. Time-to-fix for any particular category was always modelled in at least one file, but never was the distribution the same for all six files. The number of data points per category for each file varied from zero to 572. Table IX shows that the number of data points per category also varied greatly. A large percentage of categories had more than twenty data points, which means that the findings could be statistically significant. As would be expected, those categories with very few data points passed the Kolmogorov-Smirnoff Test more often than not. However, much more confidence could be placed in selected distributions which had a large number of data points and passed the Kolmogorov-Smirnoff test, than for those which only had a few data points. Table X shows that even when the categories had over twenty time-to-fix data points, time-to-fix could be modelled. Even the highest range of data points (50 or over) had distributions selected for time-to-fix for 45 percent of the categories.

A few examples of distributions selected are given in Table XI. Certain distributions appeared to be more prevalent. The log-normal distribution was chosen 42 percent of the time, as indicated in Table XII. The log-normal, the exponential, and the gamma distributions were usually selected on the basis of a large number of data points. On the other hand, the uniform and the pareto distributions were usually selected on the basis of less than ten data points.



As can be seen by the number of subcategories in Appendix F, categories such as "AA", "BB", "CC", and "DD" are quite inclusive in the type of errors that they cover. Trying to model time-to-fix within categories which are so broad in nature may not be the best approach. Possibly using subcategories, instead of major error categories, could produce more revealing information on the attributes of time-to-fix.

The problem with this approach is the loss of a large portion of the data, as is pointed out in Tables XIII and XIV. There was a significant loss of data points in all six files. Time-to-fix could not be modelled for fifty percent of the 864 possible subcategory files, because the subcategories had one or less time-to-fix data points and, therefore, distributions could not be selected. When there were enough data points for modelling, the percentage of subcategories having distributions selected decreased drastically as the number of points increased (See Table XV). Again, a variety of distributions was selected. There were a significant number of cases where distributions were selected for all six files for a particular subcategory. However, in no case was this distribution the same for all six files. A sample of the distributions selected for the subcategories is given in Table XVI. The entries in Table XVII were selected on the basis of their large number of data points. Again, the log-normal, the

exponential, and the gamma distributions were generally accepted on the basis of a large number of data points.

Table XVII points out that the uniform and pareto distributions were selected more than any of the other distributions. A closer look into this fact showed that the uniform was usually selected on the basis of fewer than ten data points. The pareto was selected approximately half the time on the basis of ten or fewer data points and the other half of the time on the basis of more than ten time-to-fix data points.

No significant difference was seen between those files measured in work days versus calendar days or calendar days versus hundredths of hours to fix. In a few cases the distributions differed, but generally the distributions stayed the same.

Table VIII

Modelling Time-To-Fix Within Categories	
File	Percentage of categories in which a distribution was selected for time-to-fix
FF1	47
FF3	82
FF4A	53
FF4B	47
FF5	82
FF5H	88
Overall	67

Table IX

Data Point Spread Within Categories

Number of data points	Percentage of categories
0-1	6
2-9	20
10-19	27
20-49	21
50-over	26

Table X

Modelling of Time-To-Fix Within Categories by the Number of Data Points

Number of data points	Percentage of categories in which a distribution was selected for time-to-fix
0-1	0
2-9	95
10-19	79
20-49	95
50 or over	42



Table XI

A Sample of Distributions Selected For Time-To-Fix Within  
Categories

---

File	Category	Data points	Distribution selected
F1	JJ	152	Gamma
F3	BB	51	Lognormal
F4A	CC	18	Gamma
F4B	KK	31	Lognormal
F5	AA	109	Lognormal
F5	PP	148	Gamma
F5	RR	144	Exponential
F5H	MM	67	Lognormal

---

Table XII

Distribution Selection For Time-To-Fix Within Major Error  
Categories :

---

Distribution	Percentage of time selected
Lognormal	42
Exponential	18
Uniform	15
Pareto	11
Gamma	9
Extreme-Value Largest	3
Extreme-Value Smallest	1
Weibull	1

---

Table XIII

## Modelling Time-To-Fix Within Subcategories

File	Percentage of subcategories in which a distribution was selected for time-to-fix
FF1	67
FF3	30
FF4A	34
FF4B	33
FF5	50
FF5H	46
Overall	43

Table XIV

## Data Point Spread Within Subcategories

Number of data points	Percentage of subcategories
0-1	50
2-9	29
10-19	10
20-49	7
50-over	4

Table XV

Modelling Time-To-Fix Within Subcategories by the Number of  
Data Points

Number of data points	Percentage of subcategories in which a distribution was selected for time-to-fix
0-1	0
2-99	96
10-19	89
20-49	79
50 or over	27

Table XVI

A Sample of Distributions Selected For Time-To-Fix Within  
Error Subcategories

File	Subcategory	Data points	Distribution selected
F1	BB100	54	Log-normal
F1	CC050	60	Log-normal
F1	GG020	36	Log-normal
F4A	BB020	46	Gamma
F4A	DD140	33	Gamma
F4B	DD010	27	Log-normal
F5	AA040	40	Log-normal
F5	BB060	173	Gamma
F5	DD050	67	Exponential
F5	PP020	116	Exponential
F5H	AA040	40	Exponential
F5H	BB020	46	Gamma
F5H	PP020	116	Log-normal



Table XVII

Distribution Selection For Time-To-Fix Within Error  
Subcategories

Distribution	Percentage of time selected
Uniform	36
Pareto	20
Log-normal	19
Exponential	13
Gamma	5
Extreme-Value-Largest	3
Extreme-Value Smallest	1
Laplace	1
Weibull	1

## Chapter VII

### Conclusions and Recommendations

#### VII.1 Conclusions

Before beginning this thesis it was not known if the existing software reliability models could be tested against one another. It was found that certain models, as given in Table II, could be tested and the criteria for which models could or could not be tested was primarily based on the available data and the basic underlying principles of each model. Utilizing maximum likelihood estimators for parameter estimations and the Likelihood Ratio Test for hypothesis testing, a computer program was written which could discriminate between the software reliability models for a given data set. One of the most important findings was the dire need for correct and usable input data before testing can begin.

The Jelinski-Moranda Geometric Model was chosen a greater number of times than any other model in Group I of Table II. The Modified Geometric Model showed even more of a predominance over Group II models. Why did this occur? Both geometric models allow an infinite number of errors to occur over the life-cycle of a computer software system. Some of the other models assume a fixed number of errors. Allowing for an infinite number of errors is a more

realistic view of the data files under study. The data files came from projects which were large and had numerous changes and updates. New errors were introduced throughout the life-cycle and new requirements placed the projects in a dynamic environment. This was noticed when File2 was joined with File1. The addition of the operational data from File2 onto the testing data from File1 altered the selection of models from the Schick-Wolverton Model for File1 to the Jelinski-Moranda Geometric Model for File1/2. The detection rate of the geometric models varies geometrically and is not fixed as in some of the other models. This feature could account for the variation in the severity of testing at any particular time and also compensating for errors that do not necessarily have an equal probability of being detected. The size of the files had no impact on whether or not the geometric models were selected. This would enable them to be applied to any size software project.

Every data base should be given a chance to be modelled and not to be prejudged regarding its distribution. Saying that all time-to-error data should be modelled by the geometric models could not be stochastically supported. A computer program, such as Program SRMOD, may be required to discriminate between models as a software project proceeds. The addition of EF2 onto EF1 to form EF1/2 is a good example of this. One model was chosen for the testing phase, while another model was chosen for the combined data from the testing and operational phases. It may be necessary to use



several different models during the life of the software package.

Modelling time-to-fix was not quite as conclusive as modelling time-to-error. It appeared that distributions for time-to-fix were project dependent. This could very well have been caused by the error categorization methodology. A certain error category could mean one thing to one contractor, but quite another to another contractor. Herein lies the problem of error categorization.

Disregarding error categories and trying to model software time-to-fix at large was unsuccessful at the 0.20 significance level. Modelling time-to-fix within major categories looked quite promising, in that time-to-fix for numerous categories had distributions selected. Trying to model time-to-fix within subcategories, did not improve the results. Rather, many data points were lost and could not be used in testing.

For many data sets the log-normal distribution was chosen. It is quite probable that with further modelling studies the log-normal distribution may play a key role in modelling time-to-fix for software projects. Other distributions that were selected quite frequently are the exponential, gamma, pareto, and uniform. Again, further testing and software error collection endeavors must be performed to validate or reject any of the findings of this study.

At best with the data that is presently available it

appears that modelling time-to-fix is software project dependent. No distribution emerged as the best for any particular file, category, or subcategory. Possibly with the use of the newer error categories better results would have been obtained.

## VII.2 Recommendations

A disease can not be cured without the knowledge of the cause. So is the case with unreliable software. Herein lies the importance of collecting software error data. How can the dilemma of unreliable software ever be solved, if its characteristics are not identified and understood? More and better error collection tools and techniques must be developed and used. Errors should be collected on all types of software projects involving higher order languages, assembly languages, batch mode, time-sharing, structured design, and the countless other software procedures. Collection of software error data may seem costly, but considering that from software error data such items as personnel training requirements, pinpointing problem programs, time-to-fix analysis, and software reliability, to mention a few, may ultimately be determined by its collection and use.

The ultimate test for software reliability models is their actual use during software development and implementation. Only then can their validity be proven. If

software reliability models are used as a project is being developed, there is more control over what data should be collected and the data's correctness. Again, the importance of continued error collection is stressed. Further analysis is required to validate the findings of this study. More and better data must be collected, so that other software reliability models can be included in a program such as Program SRMOD. A software manager could then use this program, or one similar to it, to select a software reliability model for a software package. From the model selected the software manager could determine the reliability of the software and its mean-time-to-error. On the basis of these calculations, decisions, such as whether or not to accept the software, whether or not to implement the software, or whether or not the software package will be completed on schedule, could be made. Of the two groups of software reliability models listed in Table II, how does the software manager know which group of models to use? One suggestion is that if the manager is concerned only in the occurrence of the software downtime, regardless of how many errors occurred in the interval, the model selected from Group I should be used, otherwise the model from Group II should be used.

In this study entire projects or subfunctions were examined for their reliability. A possible different approach would be to determine the reliability of each computer program and utilizing the software system



flowcharts a topological network of programs could be formed. Each program could use a software reliability model for determining its reliability, but the entire network's reliability would be based upon the principles of reliability decomposition. Another recommendation is to investigate and include into Program SRMOD, if possible, the Geometric Poisson Model referenced in Section III.1.4.

Modelling time-to-fix appears to be dependent on the standarization of error categorization. The exact definition of error categories must be standardized before any meaningful results can be obtained. From the findings of this study it appears very unlikely that a distribution will ever be found which will universally model software time-to-fix. It does seem feasible to model time-to-fix data within error categories for a specified software project. As mentioned earlier, this study used a significance level of 0.20. An investigation at perhaps a significant level of 0.10 or 0.05 may be worthwhile. Another interesting area that should be examined is the correlation between the criticality of an error and the amount of time it took to fix the error. Both items are available in the RADC files.

If one recommendation had to be chosen over all others, it would be the importance of the continuation of software error collection. A list of items that would have aided this investigation and that should be considered in future software collection endeavors is as follows:

- 1) Instruction mix
- 2) Processing rate
- 3) CPU time for each test of a computer program
- 4) Number of machine instructions
- 5) Number of source instructions
- 6) Number of tests for each computer program
- 7) The number of successful and unsuccessful tests and the order in which they occurred
- 8) Apriori probability of correcting a specific error
- 9) Date error occurred
- 10) Number of errors occurring during each test
- 11) Date error was fixed
- 12) Controls allowed over program inputs
- 13) Was seeding and tagging performed? If so, how many indigenous and induced errors were found per test
- 14) Exact dates of when the development, design, coding, testing, integration, and operational phases began
- 15) Error categories with definitions that are unambiguous
- 16) Phase in which error occurred
- 17) Program in which error occurred
- 18) Criticality of error
- 19) The length of time in actual CPU seconds and the number of days it took to fix an error
- 20) Intensity of testing
- 21) Manpower allotted for the software project
- 22) Experience of manpower allotted

Of course, it is realized that many of these items

are quite subjective in nature, and the cost of collecting all of these characteristics could be prohibitive. The economics and feasibility must be weighed for any given software development project. Only with further error data can there be any hope of quantifying the problems associated with the development and operation of software.



Appendix A  
Program SRMOD

Contained within this appendix is Program SRMOD, which was used for parameter estimation and testing of software reliability models. The program is self-documented and was written in FORTRAN for execution on a CDC6600. ANSI standards were adhered to as much as possible to aid in portability. The read and write statements may require modifications before the program can be used on another computer system. Also, subroutine ZBRENT from the IMSL subroutine library was used to compute the root of "k" for the key equation in subroutines JMG and MG. If the IMSL subroutine library is not available on the executing computer system a subroutine that can compute the root of a polynomial will have to be obtained and substituted in for ZBRENT. The memory requirement of 56K is for a large data base consisting of 2200 error records. If the data base to be tested is not that large, many of the matrices utilized in the program can be reduced, thereby reducing memory requirements. Central processing (CP) time varies considerably and is not dependent on the number of input records, but rather on the convergence rate of the key equations used in parameter estimations. For the data bases utilized in this study the CP time varied from less than 1 second to 50 seconds.

Given below is the jobstream required to execute  
Program SRMOD from source code on a CDC6600 computer. It is  
assumed that the software error input file is stored on disk  
as Tape1.

```
CAS,CM56000. T770293,CASTLE,BOX 4534
ATTACH,IMSL,ID=X654321
LIBRARY,IMSL.
ATTACH,TAPE1.
FTN.
LGO.
7/8/9 CARD
SOURCE DECK OF PROGRAM SRMOD
7/8/9 CARD
6/7/8/9 CARD (END OF JOB)
```

```
*****  
PROGRAM SRMOD  
AUTHOR: CAPT STEVE G. CASILE *****000000100  
DATE: 21 JAN 78 *****000000110  
*****000000120  
*****000000130  
*****000000140  
*****000000150  
*****000000160  
*****000000170  
*****000000180  
*****000000190  
*****000000200  
*****000000210  
*****000000220  
*****000000230  
*****000000240  
*****000000250  
*****000000260  
*****000000270  
*****000000280  
*****000000290  
*****000000300  
*****000000310  
*****000000320  
*****000000330  
*****000000340  
*****000000350  
*****000000360  
*****000000370  
*****000000380  
*****000000390  
*****000000400  
*****000000410  
*****000000420  
*****000000430  
*****000000440  
*****000000450
```

THIS PROGRAM COMPUTES PARAMETERS FOR NINE SOFTWARE RELIABILITY MODELS. THE MODELS ARE DIVIDED INTO TWO GROUPS. EACH GROUP THEN HAS ONE OF ITS MODELS SELECTED BY THE LIKELIHOOD RATIO TEST AS THE MODEL THAT BEST DESCRIBES THE ERROR DATA. FURTHER DETAILS ON THE MODELS CAN BE OBTAINED FROM THE THESIS, "SOFTWARE RELIABILITY: MODELLING TIME-TO-ERROR AND TIME-TO-FIX."

**GROUP I MODELS**

REQUIRED ONLY THE TIME BETWEEN CONSECUTIVE SOFTWARE PROBLEM REPORT DATES

- 1) JELINSKI-MORANDA DE-EUTROPHICATION
- 2) SCHICK-WOLVERTON
- 3) JELINSKI-MORANDA GEOMETRIC DE-EUTROPHICATION
- 4) WEIBUL1

**GROUP II MODELS**

REQUIRE TIME BETWEEN CONSECUTIVE SOFTWARE PROBLEM REPORT DATES AND THE NUMBER OF ERRORS OCCURRING DURING THE INTERVAL

- 1) LIPOW-JELINSKI-MORANDA DE-EUTROPHICATION
- 2) LIPOW-SCHICK-WOLVERTON





```

*****0000820
**** SUBROUTINE AND VARIABLE DICTIONARY *****0000840
****0000850
*****000860
*****000870
*****000880
*****000890
*****000900
*****000910
*****000920
*****000930
*****000940
*****000950
*****000960
*****000970
*****000980
*****000990
*****001000
*****001010
*****001020
*****001030
*****001040
*****001050
*****001060
*****001070
*****001080
*****001090
*****001100
*****001110
*****001120
*****001130
*****001140
*****001150
*****001155
*****001160

-----
*****
**** BELOW IS A LIST AND DEFINITION OF VARIABLES *****
**** USED IN THIS PROGRAM *****
*****
*****
***** BJM - VALUE OF "B" FOR JMMOD
***** BLJM - VALUE OF "B" FOR LJMMOD
***** BLSW - VALUE OF "B" FOR LSMOD
***** BMSLW - VALUE OF "B" FOR MLSW
***** COEF - COEFFICIENTS TO KEY EQUATION FOR JMG
***** COEF1 - COEFFICIENTS TO KEY EQUATION FOR MG
***** CUT - CUMULATIVE TIME THROUGH (I-1) INTERVAL
***** DIFF - TNE MINUS ELN
***** DLSN - DENOMINATOR OF LEFT SIDE OF KEY EQUATION
***** ELN - RSN TIMES DLSN
***** FLAG - USED BY PRINT ROUTINE TO DETERMINE IF
***** "N" IS GREATER THAN 10,000 + TNI
***** FT - PROBABILITY DENSITY FUNCTION FOR MODEL
***** HEADER - HEADERS FOR EACH MODEL'S OUTPUT
***** HYP0 - SUBROUTINE FOR HYPOTHESIS TESTING
***** JMG - SUBROUTINE FOR JELINSKI-MORANDA
***** GEOMETRIC MODEL
***** JMMOD - SUBROUTINE FOR JELINSKI-MORANDA
***** DE-EUTROPHICATION MODEL
***** J9 - A VALUE SIGNIFYING WHICH MODEL WAS CHOSEN
***** LJMMOD - SUBROUTINE FOR LIPOW-JELINSKI-
***** MORANDA MODEL
***** LR - A MATRIX CONTAINING THE VALUE FOR EACH
***** LSMOD - SUBROUTINE FOR LIPOW-SCHICK-WOLVERTON MODEL
***** M - A MATRIX CONTAINING THE NUMBER OF ERRORS
***** PER INTERVAL
***** MG - SUBROUTINE FOR MODIFIED GEOMETRIC MODEL
***** MLSW - SUBROUTINE FOR MODIFIED-LIPOW-SCHICK-
*****
-----

```



001170	WOLVERTON MODEL
001180	N - ESTIMATE FOR INITIAL ERROR CONTENT
001190	NI1 - CUMULATIVE NUMBER OF ERRORS OBSERVED UP
001200	THROUGH THE (I-1) TIME INTERVAL
001210	NST - COUNTER
001220	PARAM - CONTAINS VALUES FOR EACH ESTIMATED PARAMETER
001230	PHI - ESTIMATE FOR PHI
001240	PRINT - SUBROUTINE FOR PRINTING OUTPUT
001250	RSN - RIGHT SIDE OF KEY EQUATION
001290	SSTE - VALUE OF "A" FOR SUMOD
001300	STE - VALUE OF "A" FOR JMOD AND LJMOD
001310	SUM3A - PRODUCT OF TIME-TO-ERRORS FOR WM1
001320	SUM3B - PRODUCT OF THE SQUARES OF THE
001330	TIME-TO-ERRORS FOR WM1
001340	SUM4A - PRODUCT OF TIME-TO-ERRORS
001350	SUM4B - PRODUCT OF THE SQUARES OF THE
001360	TIME-TO-ERRORS FOR WM2
001370	SWITCH - USED TO PROCESS FIRST DATA POINT IN
001380	KEY EQUATION
001390	SWMA - VALUE OF "A" FOR MLSWM
001400	SUMOD - SUBROUTINE FOR SCHICK-WOLVERTON MODEL
001410	TAPE1 - INPUT DATA
001420	TE - TIME-TO-ERROR
001430	TEM - MATRIX CONTAINING ALL TIME-TO-ERROR INPUTS
001440	TEMP - TEMPORARY LOCATION FOR DIFF
001450	TNE - TOTAL NUMBER OF ERRORS
001460	TNEI - TOTAL NUMBER OF ERRORS IN INTERVAL
001470	TNI - TOTAL NUMBER OF INTERVALS
001480	WEIBUL1 - SUBROUTINE FOR WEIBUL1(WM1)
001490	WEIBUL2 - SUBROUTINE FOR WEIBUL2(WM2)
001500	
001510	



AD-A055 227

AIR FORCE INST OF TECH WRIGHT-PATTERSON AFB OHIO SCH--ETC F/G 9/2  
SOFTWARE RELIABILITY: MODELLING TIME-TO-ERROR AND TIME-TO-FIX.(U)  
MAR 78 S G CASTLE

UNCLASSIFIED

AFIT/GCS/EE/78-2

NL

2 OF 2  
AD  
A055227



```

*****001530
*****001540
*****001550
*****001560
*****001570
*****001580
*****001590
*****001600
*****001610
*****001620
*****001630
*****001640
*****001650
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*****001790
*****001800
*****001810
*****001820
*****001830
*****001840
*****001850

*****
***** DRIVER ROUTINE *****
***** CALLS EACH SUBROUTINE AND PASSES VARIABLES *****
*****
*****
*****
*****
***** PROGRAM SRMOD(OUTPUT,TAPE1) *****
***** IMPLICIT REAL(A-I,K-Z) *****
***** COMMON TEM(2200),COEF(2200),TNI,COEF1(2200),NI1(2200) *****
***** DIMENSION FLAG(9),CUT(2200),PARAM(9,4),LR(9),M(2200),HEADER(9,6) *****
***** CALL READ(TE,TNE1,CUT,TNE,STE,SSTE,SWMA,BJM,BLJM,BSW, *****
***** 1BLSW,BMLSW,M,SUM3A,SUM3B,SUM4A,SUM4B) *****
***** CALL JMOD(HEADER,TNE,BJM,STE,PARAM,LR,FLAG) *****
***** CALL SWMOD(HEADER,TNE,BSW,SSTE,PARAM,LR,FLAG) *****
***** CALL JMG(HEADER,TNE,PARAM,LR,FLAG) *****
***** CALL WEIBUL1(HEADER,SUM3A,SUM4A,TNE,PARAM,LR,FLAG) *****
***** CALL LJMOD(HEADER,TNE,BLJM,STE,M,PARAM,LR,FLAG) *****
***** CALL LSWMOD(HEADER,TNE,BLSW,SSTE,M,PARAM,LR,FLAG) *****
***** CALL MLSWM(HEADER,TNE,BMLSW,SWMA,M,PARAM,LR,CUT,FLAG) *****
***** CALL MG(HEADER,TNE,PARAM,LR,FLAG) *****
***** CALL WEIBUL2(HEADER,SUM3B,SUM4B,TNE,M,PARAM,LR,FLAG) *****
***** WRITE 10 *****
10  FORMAT(*1*,5X,"EVALUATION OF SOFTWARE RELIABILITY MODELS",/,
    $5X,"REQUIRING ONLY TIME TO ERROR AS INPUT DATA")
    CALL HYPO(LR,1,4,J9)
    CALL PRINT(PARAM,HEADER,1,4,J9,FLAG,TNE,LR)
    WRITE 20
20  FORMAT(*1*,5X,"EVALUATION OF SOFTWARE RELIABILITY MODELS",/,
    $2X,"REQUIRING TIME TO ERROR AND NUMBER OF ERRORS PER INTERVAL")
    CALL HYPO(LR,5,9,J9)
    CALL PRINT(PARAM,HEADER,5,9,J9,FLAG,TNE,LR)
    STOP
    END

```





```

40      SUM4B=SUM4B+(ALOG(TE)**2.)
        CONTINUE
        TNI=J
        TEM(J)=TE
        M(J)=TNEI
        CT=CT+TE
        TNE=TNE+TNEI
        J=J+1
        NI1(J)=TNE
        CUT(J)=CT
        GO TO 10
50      RETURN
        END

```

```

002220
002230
002240
002250
002260
002270
002280
002290
002300
002310
002320
002330
002340

```

```

*****002350
****    PARAMETER ESTIMATION FOR JELINSKI-    002360
****    MORANDA DE-EUTROPHICATION MODEL    002370
*****002380
*****002390
*****002400
*****002410
*****002420
*****002430
*****002440
****    COMPUTE ESTIMATE OF "N"    002450
*****002460
*****002470
*****002480
*****002490
*****002500
*****002510
*****002520
*****002530
*****002540
*****002550
*****002560
*****002570
*****002580
*****002590
*****002600
*****002610
*****002620
*****002630
*****002640
*****002650
*****002660
*****002670
*****002680
****    COMPUTE ESTIMATE FOR PHI    002690
*****002700
*****002700

```

```

SUBROUTINE JMMOD(HEADER,TNE,BJM,STE,PARAM,LR,FLAG)
IMPLICIT REAL(A-I,K-Z)
COMMON TEM(2200),COEF(2200),TNI,COEF1(2200),NI1(2200)
DIMENSION FLAG(9),PARAM(9,4),LR(9),HEADER(9,6)
*****002440
****    COMPUTE ESTIMATE OF "N"    002450
*****002460
*****002470
*****002480
*****002490
*****002500
*****002510
*****002520
*****002530
*****002540
*****002550
*****002560
*****002570
*****002580
*****002590
*****002600
*****002610
*****002620
*****002630
*****002640
*****002650
*****002660
*****002670
*****002680
****    COMPUTE ESTIMATE FOR PHI    002690
*****002700

```

```

RSN=NST=0.
J1=TNI
SWITCH=0.
N=TNI-.999
DLSN=(N+1.-(BJM/STE))
RSN=RSN+(1./(N-NST))
NST=NST+1.
IF(NST.LE.(TNI-1.)) GO TO 20
ELN=RSN*DLSN
DIFF=TNI-ELN
IF(DIFF.EQ.0.)GO TO 50
IF(SWITCH.EQ.0.)TEMP=DIFF
IF((DIFF.LT.0.).AND.(TEMP.GT.0.)).OR.
1((DIFF.GT.0.).AND.(TEMP.LT.0.)) GO TO 50
TEMP=DIFF
SWITCH=1.
N=N+1.
RSN=0.
NST=0.
IF(N.LT.(TNI+10000.)) GO TO 10
FLAG(1)=1.

```





```

*****002960
****    PARAMETER ESTIMATION FOR SCHICK-
****    WOLVERTON MODEL
*****002970
*****002980
*****002990
*****003000
*****003010
*****003020
*****003030
*****003040
*****003050
*****003060
*****003070
*****003080
*****003090
*****003100
*****003110
*****003120
*****003130
*****003140
*****003150
*****003160
*****003170
*****003180
*****003190
*****003200
*****003210
*****003220
*****003230
*****003240
*****003250
*****003260
*****003270
*****003280
*****003290
*****003300
*****003310

SUBROUTINE SWMOD(HEADER,TNE,BSW,SSTE,PARAM,LR,FLAG)
IMPLICIT REAL(A-I,K-Z)
COMMON TEM(2200),COEF(2200),TNI,COEF1(2200),NI1(2200)
DIMENSION FLAG(9),PARAM(9,4),LR(9),HEADER(9,6)
*****
****    COMPUTE ESTIMATE FOR "N"
*****
*****003070
*****003080
*****003090
*****003100
*****003110
*****003120
*****003130
*****003140
*****003150
*****003160
*****003170
*****003180
*****003190
*****003200
*****003210
*****003220
*****003230
*****003240
*****003250
*****003260
*****003270
*****003280
*****003290
*****003300
*****003310

    RSN=NST=0.
    J1=TNI
    SWITCH=0.
    N=TNI-.999
    10  DLSN=(N+1.-(BSW/SSTE))
    20  RSN=RSN+(1./(N-NST))
    NST=NST+1.
    IF(NST.LE.(TNI-1.)) GO TO 20
    ELN=RSN*DLSN
    DIFF=TNI-ELN
    IF(DIFF.EQ.0.)GO TO 50
    IF(SWITCH.EQ.0.)TEMP=DIFF
    IF((DIFF.LT.0.).AND.(TEMP.GT.0.)).OR.
    1  ((DIFF.GT.0.).AND.(TEMP.LT.0.)) GO TO 50
    TEMP=DIFF
    N=N+1.
    SWITCH=1.
    RSN=0.
    NST=0.
*****
****    STOP COMPUTING FOR "N" IF
****    "N" IS GREATER THAN 10,000 + TNI
*****
*****003280
*****003290
*****003300
*****003310
    IF(N.LT.(TNI+10000.))GO TO 10

```





```

*****003640
**** PARAMETER ESTIMATION FOR JELINSKI-003650
**** MORANDA GEOMETRIC MODEL003660
*****003670
*****003680
*****003690
**** SUBROUTINE JMG(HEADER,TNE,PARAM,LR,FLAG)003700
EXTERNAL F003710
REAL LR003720
COMMON TEM(2200),COEF(2200),TNI,COEF1(2200),NI1(2200)003730
DIMENSION PARAM(9,4),LR(9),HEADER(9,6)003740
*****003750
**** COMPUTE ESTIMATE OF "K"*****
*****003760
I=FIX(TNI)003770
J1=TNI003780
J=1003790
5 COEF(J)=(I-((TNI+1)/2.))*TEM(I)003800
I=I-1003810
J=J+1003820
IF(I.NE.0) GO TO 5003830
A=.9003840
B=1.1003850
FA=F(A)003860
FB=F(B)003870
IF((FA*FB).LT.0.0) GO TO 50003880
A=A-.1003890
B=B+.1003900
GO TO 10003910
50 EPS=.000001003920
NSIG=6003930
MAXFN=10000003940
CALL ZBRENT(F,EPS,NSIG,A,B,MAXFN,IER)003950
IF(IER.EQ.0)GO TO 100003960
PRINT *, IER=,IER003970
STOP003980
*****003990

```











```

75  LR(4)=LR(4)+ALOG(FT)
    CONTINUE
*****
***** RETURN
***** END

```

```

*****004870
****    PARAMETER ESTIMATION FOR LIPOW-
****    JELINSKI-MORANDA DE-EUTROPHICATION MODEL
*****004880
*****004890
*****004900
*****004910
*****004920
*****004930
*****004940
*****004950
*****004960
*****004970
*****004980
*****004990
*****005000
*****005010
*****005020
*****005030
*****005040
*****005050
*****005060
*****005070
*****005080
*****005090
*****005100
*****005110
*****005120
*****005130
*****005140
*****005150
*****005160
*****005170
*****005180
*****005190
*****005200
*****005210
*****005220

SUBROUTINE LJMOD(HEADER,TNE,BLJM,STE,M,PARAM,LR,FLAG)
IMPLICIT REAL(A-I,K-Z)
COMMON TEM(2200),COEF(2200),TNI,COEF1(2200),NI1(2200)
DIMENSION FLAG(9),PARAM(9,4),LR(9),HEADER(9,6),M(2200)
RSN=0.
*****
**** COMPUTE ESTIMATE OF "N"
*****
J1=TNI
SWITCH=0.
J=0
N=TNE-M(J1)+.1
DLSN=(N+1.-(BLJM/STE))
J=J+1
RSN=RSN+M(J)/(N-NI1(J))
IF(J.LT.TNI)GO TO 20
ELN=RSN*DLSN
DIFF=TNE-ELN
IF(DIFF.EQ.0.)GO TO 50
IF(SWITCH.EQ.0.)TEMP=DIFF
IF((DIFF.LT.0.).AND.(TEMP.GT.0)).OR.((DIFF.GT.0.).
1.AND.(TEMP.LT.0.))GO TO 50
TEMP=DIFF
SWITCH=1.
N=N+1.
RSN=0.
J=0
NST=0.
*****
**** STOP COMPUTING FOR "N" IF
**** "N" IS GREATER THAN 10,000 + TNI
*****

```





```

*****005540
***    PARAMETER ESTIMATION OF LIPOW-
***    SCHICK-WOLVERTON MODEL
*****005550
*****005560
*****005570
*****005580
*****005590
SUBROUTINE LSWMOD(HEADER,TNE,BLSW,SSTE,M,PARAM,LR,FLAG)
IMPLICIT REAL(A-I,K-Z)
COMMON TEM(2200),COEF(2200),TNI,COEF1(2200),NI1(2200)
DIMENSION FLAG(9),PARAM(9,4),LR(9),HEADER(9,6),M(2200)
*****005600
*****005610
*****005620
*****005630
*****005640
*****005650
*****005660
*****005670
*****005680
*****005690
*****005700
*****005710
*****005720
*****005730
*****005740
*****005750
*****005760
*****005770
*****005780
*****005790
*****005800
*****005810
*****005820
*****005830
*****005840
*****005850
*****005860
*****005870
*****005880
*****005890

```

COMPUTE ESTIMATE OF "N"  
 RSN=0.  
 J=0  
 J1=TNI  
 SWITCH=0.  
 N=TNE-M(J1)+.1  
 10 DLSN=(N+1-(BLSW/SSTE))  
 20 J=J+1  
 RSN=RSN+(M(J)/(N-NI1(J)))  
 IF(J.LT.TNI) GO TO 20  
 ELN=RSN\*DLSN  
 DIFF=TNE-ELN  
 IF(DIFF.EQ.0.) GO TO 50  
 IF(SWITCH.EQ.0.) TEMP=DIFF  
 IF((DIFF.LT.0.).AND.(TEMP.GT.0.)).OR.  
 1((DIFF.GT.0.).AND.(TEMP.LT.0.)) GO TO 50  
 TEMP=DIFF  
 N=N+1.  
 SWITCH=1.  
 J=0  
 RSN=0.  
 \*\*\*\*\*  
 \*\*\*\*\* STOP COMPUTING FOR "N" IF  
 \*\*\*\*\* "N" IS GREATER THAN 10,000 + TNI  
 \*\*\*\*\*

```

005900      IF(N.LT.(TNE+10000.)) GO TO 10
005910      FLAG(6)=1.
005920      *****
005930      ***** COMPUTE ESTIMATE FOR PHI
005940      *****
005950      50 PHI=TNE/(SSTE*(N+1.))-BLSW)
005960      *****
005970      *****
005980      HEADER(6,1)='LIPOW-SCHI'
005990      HEADER(6,2)='CK-WOLVERT'
006000      HEADER(6,3)='ON SOFTWAR'
006010      HEADER(6,4)='E RELIABL'
006020      HEADER(6,5)='ITY MODEL'
006030      HEADER(6,6)=10H
006040      PARAM(6,1)='N='
006050      PARAM(6,2)=N
006060      PARAM(6,3)='PHI='
006070      PARAM(6,4)=PHI
006080      *****
006090      ***** COMPUTE MAXIMUM LIKELIHOOD FUNCTIONN
006100      *****
006110      LR(6)=0.0
006120      DO 75 J=1,J1
006130      X=-PHI*(N-NI1(J))*(TEM(J)**2.)
006140      IF(X.GT.-675.)GO TO 60
006150      LR(6)=-999999.
006160      GO TO 75
006170      CONTINUE
006180      FT=PHI*(N-NI1(J))*TEM(J)*EXP(-PHI*(N-NI1(J))*(TEM(J)**2.))
006190      LR(6)=LR(6)+ALOG(FT)
006200      CONTINUE
006210      *****
006220      *****
006230      RETURN
006240      END
      ---

```



```

*****006250
****    PARAMETER ESTIMATION FOR MODIFIED-
****    LIPOW-SCHICK-WOLVERTON MODEL
*****006260
*****006270
*****006280
*****006290
*****006300
*****006310
*****006320
*****006330
*****006340
*****006350
*****006360
*****006370
*****006380
*****006390
*****006400
*****006410
*****006420
*****006430
*****006440
*****006450
*****006460
*****006470
*****006480
*****006490
*****006500
*****006510
*****006520
*****006530
*****006540
*****006550
*****006560
*****006570
*****006580
*****006590
*****006600

SUBROUTINE MLSWM(HEADER,TNE,BMLSW,SWMA,M,PARAM,LR,CUT,FLAG)
IMPLICIT REAL(A-I,K-Z)
COMMON TEM(2200),COEF(2200),TNI,COEF1(2200),NI1(2200)
DIMENSION FLAG(9),CUT(2200),PARAM(9,4),LR(9),HEADER(9,6),M(2200)
*****
****    COMPUTE ESTIMATE OF "N"
*****
RSN=0.
J=0
J1=TNI
SWITCH=0.
N=TNE-M(J1)+.1
DLSN=(N+1-(BMLSW/SWMA))
J=J+1
RSN=RSN+(M(J)/(N-NI1(J)))
IF(J.LT.TNI) GO TO 20
ELN=RSN*DLSN
DIFF=TNE-ELN
IF(DIFF.EQ.0.)GO TO 50
IF(SWITCH.EQ.0.)TEMP=DIFF
IF(((DIFF.LT.0.).AND.(TEMP.GT.0.)).OR.
1((DIFF.GT.0.).AND.(TEMP.LT.0.)))GO TO 50
TEMP=DIFF
SWITCH=1.
N=N+1.
RSN=0.
J=0
*****
****    STOP COMPUTING FOR "N" IF
****    "N" IS GREATER THAN 10,000 + TNI
*****

```



```

006610      IF(N.LT.(TNE+10000.))GO TO 10
006620      FLAG(7)=1.
006630      *****
006640      ***** COMPUTE ESTIMATE FOR PHI
006650      *****
006660      50 PHI=TNE/(SUMAX(N+1)-BMLSW)
006670      *****
006680      *****
006690      HEADER(7,1)="MODIFIED-L."
006700      HEADER(7,2)="IFOW-SCHIC."
006710      HEADER(7,3)="K-WOLVERTO."
006720      HEADER(7,4)="N SOFTWARE."
006730      HEADER(7,5)=" RELIABILI."
006740      HEADER(7,6)="TY MODEL ."
006750      PARAM(7,1)="N="
006760      PARAM(7,2)=N
006770      PARAM(7,3)="PHI="
006780      PARAM(7,4)=PHI
006790      *****
006800      ***** COMPUTE MAXIMUM LIKELIHOOD FUNCTION
006810      *****
006820      LR(7)=0.0
006830      DO 75 J=1,J1
006840      FT=PHI*(N-NI1(J))*(CUT(J)+(TEM(J)/2.))*EXP(-PHI*(N-NI1(J)))*
006850      $ (CUT(J)+(TEM(J)/2.))*TEM(J)
006860      LR(7)=LR(7)+ALOG(FT)
006870      75 CONTINUE
006880      *****
006890      *****
006900      RETURN
006910      END

```

```

*****006920
****    PARAMETER ESTIMATION FOR          006930
****    MODIFIED GEOMETRIC MODEL          006940
*****006950
*****006960
SUBROUTINE MG(HEADER,TNE,PARAM,LR,FLAG)
EXTERNAL F1
REAL NI1,LR
COMMON TEM(2200),COEF(2200),TNI,COEF1(2200),NI1(2200)
DIMENSION PARAM(9,4),LR(9),HEADER(9,6)
*****007000
*****007010
****    COMPUTE ESTIMATE OF "K"
*****007020
*****007030
*****007040
J1=TNI
TNI1=0.0
I=IFIX(TNI)
DO 1 N=1,I
  TNI1=TNI1+NI1(N)
  CONTINUE
  J=1
  5 COEF1(J)=(NI1(J)-(TNI1/TNI))*TEM(I)
    J=J+1
    IF(J.LE.I)GO TO 5
    A=.9
    B=1.1
    FA=F1(A)
    FB=F1(B)
    IF((FA*FB).LT.0.0) GO TO 50
    A=A-.1
    B=B+.1
    GO TO 10
  50 EPS=.000001
    NSIG=6
    MAXFN=10000
    CALL ZBRENT(F1,EPS,NSIG,A,B,MAXFN,IER)
    IF(IER.EQ.0)GO TO 100
    PRINT *, " IER=",IER
*****007270

```

```

007280 STOP
007290 *****
007300 *** COMPUTE ESTIMATE FOR "D"
007310 *****
007320 100 DD=0.0
007330 N=FIX(TNI)
007340 DO 200 I=1,N
007350 DD=DD+B*(NI1(I))*TEM(I)
007360 200 CONTINUE
007370 D=TNI/DD
007380 *****
007390 ***
007400 HEADER(8,1)="MODIFIED G"
007410 HEADER(8,2)="EOMETRIC M"
007420 HEADER(8,3)="ODEL"
007430 HEADER(8,4)=" "
007440 HEADER(8,5)=" "
007450 HEADER(8,6)=" "
007460 PARAM(8,1)="D="
007470 PARAM(8,2)=D
007480 PARAM(8,3)="K="
007490 PARAM(8,4)=B
007500 *****
007510 *** COMPUTE MAXIMUM LIKELIHOOD FUNCTION
007520 *****
007530 LR(8)=0.0
007540 DO 75 J=1,J1
007550 FT=D*(B*NI1(J))*EXP(-D*(B*NI1(J))*TEM(J))
007560 LR(8)=LR(8)+ALOG(FT)
007570 75 CONTINUE
007580 *****
007590 ***
007600 RETURN
007610 END

```



```

*****007620
*** COMPUTES f(i) FOR KEY EQUATION 007630
*** TO ESTIMATE "K" 007640
*****007650
*****007660
*****
FUNCTION F1(X) 007670
REAL NI1 007680
COMMON TEM(2200),COEF(2200),TNI,COEF1(2200),NI1(2200) 007690
ITNI=IFIX(TNI) 007700
F1=0.0 007710
DO 1 J=1,ITNI 007720
F1=F1+(COEF1(J))*(X**NI1(J)) 007730
CONTINUE 007740
RETURN 007750
END 007760
STOP

```

1

```

*****007770
****    PARAMTER ESTIMATION FOR WEIBUL2    007780
*****007790
****    007800
        SUBROUTINE WEIBUL2(HEADER,SUM3B,SUM4B,TNE,M,PARAM,LR,FLAG)    007810
        IMPLICIT REAL(A-I,K-Z)    007820
        COMMON TEN(2200),COEF(2200),INI,COEF1(2200),NI1(2200)    007830
        DIMENSION M(2200),PARAM(9,4),LR(9),HEADER(9,6)    007840
        *****007850
        ***** ESTIMATION OF SHAPE AND SCALE PARAMETERS *****007860
        *****007870
        J1=INI    007880
        A=1./(((SUM4B/(TNE-1.)-(SUM3B**2.)/(TNE*(TNE-1)))*( .6079271))**.5)007890
        B=EXP(SUM3B/TNE+.5772/A)    007900
        *****007910
        *****007920
        HEADER(9,1)="WEIBULL SO"    007930
        HEADER(9,2)="FTWARE REL"    007940
        HEADER(9,3)="IABILITY M"    007950
        HEADER(9,4)="ODEL"    007960
        HEADER(9,5)=10H    007970
        HEADER(9,6)=10H    007980
        PARAM(9,1)="ALPHA="    007990
        PARAM(9,2)=A    008000
        PARAM(9,3)="BETA="    008010
        PARAM(9,4)=B    008020
        *****008030
        ***** COMPUTE MAXIMUM LIKELIHOOD FUNCTION *****008040
        *****008050
        LR(9)=0.0    008060
        DO 75 J=1,J1    008070
        J2=M(J)    008080
        DO 70 J3=1,J2    008090
        X=-((TEM(J)/B)**A)    008100
        IF(X.GT.-675.)GO TO 50    008110
        LR(9)=-99999.    008120

```

0008130  
0008140  
0008150  
0008160  
0008170  
0008180  
0008190  
0008200  
0008210  
0008220



```

*****008230
****      HYPOTHESIS TESTING008240
****      SELECTS BEST DISTRIBUTION USING008250
****      LIKELIHOOD RATIO TEST008260
*****008270
*****SUBROUTINE HYPO(LR,J,K,L)
      REAL LR008280
      DIMENSION LR(9)008290
      L=J008300
      DO 10 I=J,K008310
      IF(LR(L).LT.LR(I))L=I008320
      CONTINUE008330
      RETURN008340
      END008350
      10008360

```

```

*****008370
**** PRINT SUBROUTINE 008380
**** PRINTS HEADERS,PARAMETERS,AND DISTRIBUTION 008390
**** SELECTED 008400
*****008410
***** SUBROUTINE PRINT(PARAM,HEADER,J,J1,J9,FLAG,TNE,LR) 008420
***** IMPLICIT REAL(A-I,K-Z) 008430
***** COMMON TEM(2200),COEF(2200),TNI,COEF1(2200),NI1(2200) 008440
***** DIMENSION FLAG(9),PARAM(9,4),LR(9),HEADER(9,6) 008450
***** WRITE 10,TNE,TNI 008460
10 FORMAT(/,1X," TOTAL NUMBER OF ERRORS TO DATE = ",F6.0,/, 008470
$2X,"TOTAL NUMBER OF INTERVALS = ",F6.0) 008480
20 FORMAT(/,1X,"**CONVERGENCE WAS NOT REACHED**",/, 008490
$1X,"**CALCULATIONS WERE STOPPED AT ",/5X,"(N=10000+TOTAL" 008500
$ " NUMBER OF #STOPS#)**") 008510
***** WRITE 25 008520
25 FORMAT(/,1X,"PARAMETER ESTIMATIONS FOR THE TESTED MODELS ARE:") 008530
***** DO 50 J4=J,J1 008540
***** WRITE 40,(HEADER(J4,J2),J2=1,6) 008550
40 FORMAT(/,1X,6A10) 008560
***** IF(FLAG(J4).EQ.0.0)GO TO 30 008570
***** WRITE 20 008580
***** CONTINUE 008590
***** WRITE 45,(PARAM(J4,J2),J2=1,4),LR(J4) 008600
45 FORMAT(/,1X,A6,F13.7,3X,A5,F12.9,3X,"LLR=",F14.2) 008610
***** CONTINUE 008620
***** WRITE 60,(HEADER(J9,J2),J2=1,6) 008630
60 FORMAT(/,1X,"THE LIKELIHOOD RATIO TEST HAS SELECTED:", 008640
$/1X,6A10) 008650
***** RETURN 008660
***** END 008670

```

Appendix B

Sample Input for Program SRMOD

Given within this appendix is file F5C in its entirety and it represents typical input for Program SRMOD. The first entry of each record indicates the time interval between successive software problem reports. The second entry represents the number of errors occurring within this time interval.



Sample Input for Program SRMOD

1.	1.
9.	1.
76.	1.
8.	1.
33.	1.
14.	1.
1.	5.
1.	1.
5.	2.
6.	2.
6.	1.
7.	2.
1.	1.
3.	2.
4.	2.
2.	3.
5.	1.
2.	5.
4.	2.
10.	1.
10.	1.
1.	1.
1.	1.
1.	3.
5.	1.
2.	3.
2.	1.
11.	1.
1.	1.
8.	1.
29.	1.
20.	3.
4.	1.
11.	3.
4.	2.
2.	2.
7.	1.
8.	2.
4.	1.
7.	2.
1.	2.
1.	1.
1.	1.
4.	1.
1.	1.
5.	1.
2.	1.
7.	1.
2.	1.
4.	1.
2.	1.

Appendix C  
Program SRMOD Output

Within this appendix is the output from Program SRMOD for each of the twenty input files. Each output is labelled as to which error file it pertains to. There are two outputs for each file. One for Group I models and one for Group II models. "LLR" represents the natural logarithm of the maximum likelihood function. In some cases the maximum likelihood function became so small it was considered equal to zero by the computer and subsequently the logarithm could not be taken. To resolve this situation "LLR" was set equal to the arbitrary number -999999.0 whenever the logarithm could not be taken for this reason. The next 40 pages are the actual outputs from Program SRMOD. All parameters are the same as those used in the text of this thesis.

FILE: EF1

EVALUATION OF GROUP I SOFTWARE RELIABILITY MODELS  
REQUIRING ONLY TIME TO ERROR AS INPUT DATA

TOTAL NUMBER OF ERRORS TO DATE = 2172.

TOTAL NUMBER OF INTERVALS = 152.

PARAMETER ESTIMATIONS FOR THE TESTED MODELS ARE:

JELINSKI-MORANDA SOFTWARE RELIABILITY MODEL

N= 248.0010000 PHI= .004852014 LLR= -184.28

SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

N= 152.0010000 PHI= .018812043 LLR= -127.13

JELINSKI-MORANDA GEOMETRIC SOFTWARE RELIABILITY MODEL

D= 1.1727845 K= .994996064 LLR= -185.34

WEIBULL SOFTWARE RELIABILITY MODEL

ALPHA= 3.5433276 BETA= 1.288208006 LLR= -1000227.17

THE LIKELIHOOD RATIO TEST HAS SELECTED:  
SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

..



FILE: EF1

EVALUATION OF GROUP II SOFTWARE RELIABILITY MODELS  
REQUIRING TIME TO ERROR AND NUMBER OF ERRORS PER INTERVAL

TOTAL NUMBER OF ERRORS TO DATE = 2172.  
TOTAL NUMBER OF INTERVALS = 152.

PARAMETER ESTIMATIONS FOR THE TESTED MODELS ARE:

LIPOW-JELINSKI-MORANDA SOFTWARE RELIABILITY MODEL

N= 2546.1000000 PHI = .009734999 LLR= -1811.59

LIPOW-SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

N= 2172.1000000 PHI= .024776264 LLR= -3937.13

MODIFIED-LIPOW-SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

N= 2176.1000000 PHI= .000306270 LLR= -1816.24

MODIFIED GEOMETRIC SOFTWARE RELIABILITY MODEL

D= .7792413 K= 1.000000225 LLR= -189.87

WEIBULL SOFTWARE RELIABILITY MODEL

ALPHA= 8.1579818 BETA= 1.104085712 LLR= -99999.00

THE LIKELIHOOD RATIO TEST HAS SELECTED:  
MODIFIED GEOMETRIC SOFTWARE RELIABILITY MODEL

..

FILE: EF2

EVALUATION OF GROUP I SOFTWARE RELIABILITY MODELS  
REQUIRING ONLY TIME TO ERROR AS INPUT DATA

TOTAL NUMBER OF ERRORS TO DATE = 198.  
TOTAL NUMBER OF INTERVALS = 86.

PARAMETER ESTIMATIONS FOR THE TESTED MODELS ARE:

JELINSKI-MORANDA SOFTWARE RELIABILITY MODEL

\*\*CONVERGENCE WAS NOT REACHED\*\*  
\*\*CALCULATIONS WERE STOPPED AT  
(N=10000+TOTAL NUMBER OF #STOPS#)\*\*

N= 10086.0010000 PHI= .000034624 LLR= -176.84

SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

\*\*CONVERGENCE WAS NOT REACHED\*\*  
\*\*CALCULATIONS WERE STOPPED AT  
(N=10000+TOTAL NUMBER OF #STOPS#)\*\*

N= 10086.0010000 PHI= .000005879 LLR= -278.70

JELINSKI-MORANDA GEOMETRIC SOFTWARE RELIABILITY MODEL

D= .1843821 K= 1.017790064 LLR= -166.95

WEIBULL SOFTWARE RELIABILITY MODEL

ALPHA= 1.6343261 BETA= 2.564747416 LLR= -274.50

THE LIKELIHOOD RATIO TEST HAS SELECTED:  
JELINSKI-MORANDA GEOMETRIC SOFTWARE RELIABILITY MODEL

..

FILE: EF2

EVALUATION OF GROUP II SOFTWARE RELIABILITY MODELS  
REQUIRING TIME TO ERROR AND NUMBER OF ERRORS PER INTERVAL

TOTAL NUMBER OF ERRORS TO DATE = 198.

TOTAL NUMBER OF INTERVALS = 86.

PARAMETER ESTIMATIONS FOR THE TESTED MODELS ARE:

LIPOW-JELINSKI-MORANDA SOFTWARE RELIABILITY MODEL

\*\*CONVERGENCE WAS NOT REACHED\*\*

\*\*CALCULATIONS WERE STOPPED AT

(N=10000+TOTAL NUMBER OF #STOPS#)\*\*

N= 10198.1000000 PHI = .000079119 LLR= -217.30

LIPOW-SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

\*\*CONVERGENCE WAS NOT REACHED\*\*

\*\*CALCULATIONS WERE STOPPED AT

(N=10000+TOTAL NUMBER OF #STOPS#)\*\*

N= 10198.1000000 PHI= .000013402 LLR= -517.36

MODIFIED-LIPOW-SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

N= 997.1000000 PHI= .000007243 LLR= -212.46

MODIFIED GEOMETRIC SOFTWARE RELIABILITY MODEL

D= .3481729 K= 1.000000225 LLR= -176.73

WEIBULL SOFTWARE RELIABILITY MODEL

ALPHA= 1.7505832 BETA= 2.317399574 LLR= -633.13

THE LIKELIHOOD RATIO TEST HAS SELECTED:  
MODIFIED GEOMETRIC SOFTWARE RELIABILITY MODEL

..



FILE: EF1/2

EVALUATION OF GROUP I SOFTWARE RELIABILITY MODELS  
REQUIRING ONLY TIME TO ERROR AS INPUT DATA

TOTAL NUMBER OF ERRORS TO DATE = 2370.  
TOTAL NUMBER OF INTERVALS = 238.

PARAMETER ESTIMATIONS FOR THE TESTED MODELS ARE:

JELINSKI-MORANDA SOFTWARE RELIABILITY MODEL

N= 362.0010000 PHI= .002594701 LLR= -357.52

SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

N= 263.0010000 PHI= .001593007 LLR= -1000157.19

JELINSKI-MORANDA GEOMETRIC SOFTWARE RELIABILITY MODEL

D= 1.1039887 K= .994998539 LLR= -355.86

WEIBULL SOFTWARE RELIABILITY MODEL

ALPHA= 2.2821522 BETA= 1.658591296 LLR= -1000139.45

THE LIKELIHOOD RATIO TEST HAS SELECTED:  
JELINSKI-MORANDA GEOMETRIC SOFTWARE RELIABILITY MODEL

..

FILE: EF1/2

EVALUATION OF GROUP II SOFTWARE RELIABILITY MODELS  
REQUIRING TIME TO ERROR AND NUMBER OF ERRORS PER INTERVAL

TOTAL NUMBER OF ERRORS TO DATE = 2370.

TOTAL NUMBER OF INTERVALS = 238.

PARAMETER ESTIMATIONS FOR THE TESTED MODELS ARE:

LIPOW-JELINSKI-MORANDA SOFTWARE RELIABILITY MODEL

N= 2401.1000000 PHI = .010385982 LLR= -2012.38

LIPOW-SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

N= 2370.1000000 PHI= .006958987 LLR= -1000229.81

MODIFIED-LIPOW-SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

N= 2370.1000000 PHI= .000131312 LLR= -1979.38

MODIFIED GEOMETRIC SOFTWARE RELIABILITY MODEL

D= .5774299 K= 1.000000225 LLR= -368.62

WEIBULL SOFTWARE RELIABILITY MODEL

ALPHA= 4.5476435 BETA= 1.213738644 LLR= -104017.74

THE LIKELIHOOD RATIO TEST HAS SELECTED:  
MODIFIED GEOMETRIC SOFTWARE RELIABILITY MODEL

..

FILE: EF3A

EVALUATION OF GROUP I SOFTWARE RELIABILITY MODELS  
REQUIRING ONLY TIME TO ERROR AS INPUT DATA

TOTAL NUMBER OF ERRORS TO DATE = 144.  
TOTAL NUMBER OF INTERVALS = 54.

PARAMETER ESTIMATIONS FOR THE TESTED MODELS ARE:

JELINSKI-MORANDA SOFTWARE RELIABILITY MODEL

\*\*CONVERGENCE WAS NOT REACHED\*\*  
\*\*CALCULATIONS WERE STOPPED AT  
(N=10000+TOTAL NUMBER OF #STOPS#)\*\*

N= 10054.0010000 PHI= .000033415 LLR= -113.04

SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

\*\*CONVERGENCE WAS NOT REACHED\*\*  
\*\*CALCULATIONS WERE STOPPED AT  
(N=10000+TOTAL NUMBER OF #STOPS#)\*\*

N= 10054.0010000 PHI= .000004598 LLR= -190.19

JELINSKI-MORANDA GEOMETRIC SOFTWARE RELIABILITY MODEL

D= .1882861 K= 1.027401418 LLR= -105.48

WEIBULL SOFTWARE RELIABILITY MODEL

ALPHA= 1.5693922 BETA= 2.515452292 LLR= -183.00

THE LIKELIHOOD RATIO TEST HAS SELECTED:  
JELINSKI-MORANDA GEOMETRIC SOFTWARE RELIABILITY MODEL

..



FILE: EF3A

EVALUATION OF GROUP II SOFTWARE RELIABILITY MODELS  
REQUIRING TIME TO ERROR AND NUMBER OF ERRORS PER INTERVAL

TOTAL NUMBER OF ERRORS TO DATE = 144.  
TOTAL NUMBER OF INTERVALS = 54.

PARAMETER ESTIMATIONS FOR THE TESTED MODELS ARE:

LIPOW-JELINSKI-MORANDA SOFTWARE RELIABILITY MODEL

\*\*CONVERGENCE WAS NOT REACHED\*\*  
\*\*CALCULATIONS WERE STOPPED AT  
(N=10000+TOTAL NUMBER OF #STOPS#)\*\*

N= 10144.1000000 PHI = .000088541 LLR= -150.17

LIPOW-SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

\*\*CONVERGENCE WAS NOT REACHED\*\*  
\*\*CALCULATIONS WERE STOPPED AT  
(N=10000+TOTAL NUMBER OF #STOPS#)\*\*

N= 10144.1000000 PHI= .000012158 LLR= -371.43

MODIFIED-LIPOW-SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

\*\*CONVERGENCE WAS NOT REACHED\*\*  
\*\*CALCULATIONS WERE STOPPED AT  
(N=10000+TOTAL NUMBER OF #STOPS#)\*\*

N= 10144.1000000 PHI= .000001103 LLR= -136.65

MODIFIED GEOMETRIC SOFTWARE RELIABILITY MODEL

D= .3354005 K= 1.000000225 LLR= -112.99

WEIBULL SOFTWARE RELIABILITY MODEL

ALPHA= 1.8409500 BETA= 1.995204713 LLR= -598.27

THE LIKELIHOOD RATIO TEST HAS SELECTED:  
MODIFIED GEOMETRIC SOFTWARE RELIABILITY MODEL

..

FILE: EF3B

EVALUATION OF GROUP I SOFTWARE RELIABILITY MODELS  
REQUIRING ONLY TIME TO ERROR AS INPUT DATA

TOTAL NUMBER OF ERRORS TO DATE = 75.  
TOTAL NUMBER OF INTERVALS = 30.

PARAMETER ESTIMATIONS FOR THE TESTED MODELS ARE:

JELINSKI-MORANDA SOFTWARE RELIABILITY MODEL

\*\*CONVERGENCE WAS NOT REACHED\*\*  
\*\*CALCULATIONS WERE STOPPED AT  
(N=10000+TOTAL NUMBER OF #STOPS#)\*\*

N= 10030.0010000 PHI= .000034818 LLR= -61.60

SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

\*\*CONVERGENCE WAS NOT REACHED\*\*  
\*\*CALCULATIONS WERE STOPPED AT  
(N=10000+TOTAL NUMBER OF #STOPS#)\*\*

N= 10030.0010000 PHI= .000009208 LLR= -82.15

JELINSKI-MORANDA GEOMETRIC SOFTWARE RELIABILITY MODEL

D= .2170610 K= 1.037888981 LLR= -59.65

WEIBULL SOFTWARE RELIABILITY MODEL

ALPHA= 1.5983478 BETA= 2.735939264 LLR= -74.64

THE LIKELIHOOD RATIO TEST HAS SELECTED:  
JELINSKI-MORANDA GEOMETRIC SOFTWARE RELIABILITY MODEL

..

FILE: EF3B

EVALUATION OF GROUP II SOFTWARE RELIABILITY MODELS  
REQUIRING TIME TO ERROR AND NUMBER OF ERRORS PER INTERVAL

TOTAL NUMBER OF ERRORS TO DATE = 75.  
TOTAL NUMBER OF INTERVALS = 30.

PARAMETER ESTIMATIONS FOR THE TESTED MODELS ARE:

LIPOW-JELINSKI-MORANDA SOFTWARE RELIABILITY MODEL

\*\*CONVERGENCE WAS NOT REACHED\*\*  
\*\*CALCULATIONS WERE STOPPED AT  
(N=10000+TOTAL NUMBER OF #STOPS#)\*\*

N= 10075.1000000 PHI = .000086801 LLR= -79.13

LIPOW-SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

\*\*CONVERGENCE WAS NOT REACHED\*\*  
\*\*CALCULATIONS WERE STOPPED AT  
(N=10000+TOTAL NUMBER OF #STOPS#)\*\*

N= 10075.1000000 PHI= .000022932 LLR= -174.71

MODIFIED-LIPOW-SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

N= 115.1000000 PHI= .000277906 LLR= -78.93

MODIFIED GEOMETRIC SOFTWARE RELIABILITY MODEL

D= .3488373 K= .999999994 LLR= -61.59

WEIBULL SOFTWARE RELIABILITY MODEL

ALPHA= 1.3858821 BETA= 3.162500962 LLR= -200.62

THE LIKELIHOOD RATIO TEST HAS SELECTED:  
MODIFIED GEOMETRIC SOFTWARE RELIABILITY MODEL

..



FILE: EF4

EVALUATION OF GROUP I SOFTWARE RELIABILITY MODELS  
REQUIRING ONLY TIME TO ERROR AS INPUT DATA

TOTAL NUMBER OF ERRORS TO DATE = 1254.

TOTAL NUMBER OF INTERVALS = 435.

PARAMETER ESTIMATIONS FOR THE TESTED MODELS ARE:

JELINSKI-MORANDA SOFTWARE RELIABILITY MODEL

N= 604.0010000 PHI= .001086245 LLR= -837.44

SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

N= 436.0010000 PHI= .001028449 LLR= -1000688.93

JELINSKI-MORANDA GEOMETRIC SOFTWARE RELIABILITY MODEL

D= .6017035 K= .997989480 LLR= -845.95

WEIBULL SOFTWARE RELIABILITY MODEL

ALPHA= 1.6803426 BETA= 2.538534110 LLR= -1246.52

THE LIKELIHOOD RATIO TEST HAS SELECTED:  
JELINSKI-MORANDA SOFTWARE RELIABILITY MODEL

..

FILE: EF4

EVALUATION OF GROUP II SOFTWARE RELIABILITY MODELS  
REQUIRING TIME TO ERROR AND NUMBER OF ERRORS PER INTERVAL

TOTAL NUMBER OF ERRORS TO DATE = 1254.  
TOTAL NUMBER OF INTERVALS = 435.

PARAMETER ESTIMATIONS FOR THE TESTED MODELS ARE:

LIPOW-JELINSKI-MORANDA SOFTWARE RELIABILITY MODEL

N= 1571.1000000 PHI = .001362447 LLR= -1204.93

LIPOW-SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

N= 1256.1000000 PHI= .001109199 LLR= -2600.13

MODIFIED-LIPOW-SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

N= 1259.1000000 PHI= .000007872 LLR= -1179.66

MODIFIED GEOMETRIC SOFTWARE RELIABILITY MODEL

D= .3714118 K= 1.000000225 LLR= -865.78

WEIBULL SOFTWARE RELIABILITY MODEL

ALPHA= 1.8039613 BETA= 2.408449833 LLR= -3503.76

THE LIKELIHOOD RATIO TEST HAS SELECTED:  
MODIFIED GEOMETRIC SOFTWARE RELIABILITY MODEL

..

FILE: EF5A

EVALUATION OF GROUP I SOFTWARE RELIABILITY MODELS  
REQUIRING ONLY TIME TO ERROR AS INPUT DATA

TOTAL NUMBER OF ERRORS TO DATE = 432.  
TOTAL NUMBER OF INTERVALS = 149.

PARAMETER ESTIMATIONS FOR THE TESTED MODELS ARE:

JELINSKI-MORANDA SOFTWARE RELIABILITY MODEL

N= 931.0010000 PHI= .000476236 LLR= -282.72

SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

N= 694.0010000 PHI= .000300735 LLR= -303.79

JELINSKI-MORANDA GEOMETRIC SOFTWARE RELIABILITY MODEL

D= .4395602 K= .998978879 LLR= -282.74

WEIBULL SOFTWARE RELIABILITY MODEL

ALPHA= 1.9040927 BETA= 2.576061061 LLR= -310.03

THE LIKELIHOOD RATIO TEST HAS SELECTED:  
JELINSKI-MORANDA SOFTWARE RELIABILITY MODEL  
..



FILE: EF5A

EVALUATION OF GROUP II SOFTWARE RELIABILITY MODELS  
REQUIRING TIME TO ERROR AND NUMBER OF ERRORS PER INTERVAL

TOTAL NUMBER OF ERRORS TO DATE = 432.

TOTAL NUMBER OF INTERVALS = 149.

PARAMETER ESTIMATIONS FOR THE TESTED MODELS ARE:

LIPOW-JELINSKI-MORANDA SOFTWARE RELIABILITY MODEL

N= 1080.1000000 PHI = .001391441 LLR= -408.04

LIPOW-SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

N= 987.1000000 PHI= .000714475 LLR= -861.16

MODIFIED-LIPOW-SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

N= 454.1000000 PHI= .000044175 LLR= -420.13

MODIFIED GEOMETRIC SOFTWARE RELIABILITY MODEL

D= .4070826 K= 1.000000225 LLR= -282.90

WEIBULL SOFTWARE RELIABILITY MODEL

ALPHA= 1.9463397 BETA= 2.729025073 LLR= -832.35

THE LIKELIHOOD RATIO TEST HAS SELECTED:  
MODIFIED GEOMETRIC SOFTWARE RELIABILITY MODEL

..

FILE: EFSB

EVALUATION OF GROUP I SOFTWARE RELIABILITY MODELS  
REQUIRING ONLY TIME TO ERROR AS INPUT DATA

TOTAL NUMBER OF ERRORS TO DATE = 293.

TOTAL NUMBER OF INTERVALS = 146.

PARAMETER ESTIMATIONS FOR THE TESTED MODELS ARE:

JELINSKI-MORANDA SOFTWARE RELIABILITY MODEL

\*\*CONVERGENCE WAS NOT REACHED\*\*

\*\*CALCULATIONS WERE STOPPED AT

(N=10000+TOTAL NUMBER OF #STOPS#)\*\*

N= 10146.0010000 PHI= .000019503 LLR= -383.58

SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

\*\*CONVERGENCE WAS NOT REACHED\*\*

\*\*CALCULATIONS WERE STOPPED AT

(N=10000+TOTAL NUMBER OF #STOPS#)\*\*

N= 10146.0010000 PHI= .000001812 LLR= -1000333.21

JELINSKI-MORANDA GEOMETRIC SOFTWARE RELIABILITY MODEL

D= .1121143 K= 1.008732806 LLR= -373.45

WEIBULL SOFTWARE RELIABILITY MODEL

ALPHA= 1.3167573 BETA= 4.282208435 LLR= -442.44

THE LIKELIHOOD RATIO TEST HAS SELECTED:

JELINSKI-MORANDA GEOMETRIC SOFTWARE RELIABILITY MODEL

..

FILE: EF5B

EVALUATION OF GROUP II SOFTWARE RELIABILITY MODELS  
REQUIRING TIME TO ERROR AND NUMBER OF ERRORS PER INTERVAL

TOTAL NUMBER OF ERRORS TO DATE = 293.  
TOTAL NUMBER OF INTERVALS = 146.

PARAMETER ESTIMATIONS FOR THE TESTED MODELS ARE:

LIPOW-JELINSKI-MORANDA SOFTWARE RELIABILITY MODEL

\*\*CONVERGENCE WAS NOT REACHED\*\*  
\*\*CALCULATIONS WERE STOPPED AT  
(N=10000+TOTAL NUMBER OF #STOPS#)\*\*

N= 10293.1000000 PHI = .000038787 LLR= -429.08

LIPOW-SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

\*\*CONVERGENCE WAS NOT REACHED\*\*  
\*\*CALCULATIONS WERE STOPPED AT  
(N=10000+TOTAL NUMBER OF #STOPS#)\*\*

N= 10293.1000000 PHI= .000003599 LLR= -920.82

MODIFIED-LIPOW-SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

N= 915.1000000 PHI= .000001399 LLR= -436.78

MODIFIED GEOMETRIC SOFTWARE RELIABILITY MODEL

D= .1967605 K= 1.000000225 LLR= -383.36

WEIBULL SOFTWARE RELIABILITY MODEL

ALPHA= 1.4295102 BETA= 3.463712479 LLR= -832.92

THE LIKELIHOOD RATIO TEST HAS SELECTED:  
MODIFIED GEOMETRIC SOFTWARE RELIABILITY MODEL

..



FILE: EF5C

EVALUATION OF GROUP I SOFTWARE RELIABILITY MODELS  
REQUIRING ONLY TIME TO ERROR AS INPUT DATA

TOTAL NUMBER OF ERRORS TO DATE = 80.

TOTAL NUMBER OF INTERVALS = 51.

PARAMETER ESTIMATIONS FOR THE TESTED MODELS ARE:

JELINSKI-MORANDA SOFTWARE RELIABILITY MODEL

\*\*CONVERGENCE WAS NOT REACHED\*\*

\*\*CALCULATIONS WERE STOPPED AT  
(N=10000+TOTAL NUMBER OF #STOPS#)\*\*

N= 10051.0010000 PHI= .000013889 LLR= -151.54

SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

\*\*CONVERGENCE WAS NOT REACHED\*\*

\*\*CALCULATIONS WERE STOPPED AT  
(N=10000+TOTAL NUMBER OF #STOPS#)\*\*

N= 10051.0010000 PHI= .000001064 LLR= -213.77

JELINSKI-MORANDA GEOMETRIC SOFTWARE RELIABILITY MODEL

D= .0756303 K= 1.028589567 LLR= -146.74

WEIBULL SOFTWARE RELIABILITY MODEL

ALPHA= 1.2148178 BETA= 6.199801215 LLR= -161.05

THE LIKELIHOOD RATIO TEST HAS SELECTED:

JELINSKI-MORANDA GEOMETRIC SOFTWARE RELIABILITY MODEL

..

..

FILE: EF5C

EVALUATION OF GROUP II SOFTWARE RELIABILITY MODELS  
REQUIRING TIME TO ERROR AND NUMBER OF ERRORS PER INTERVAL

TOTAL NUMBER OF ERRORS TO DATE = 80.  
TOTAL NUMBER OF INTERVALS = 51.

PARAMETER ESTIMATIONS FOR THE TESTED MODELS ARE:

LIPOW-JELINSKI-MORANDA SOFTWARE RELIABILITY MODEL

\*\*CONVERGENCE WAS NOT REACHED\*\*  
\*\*CALCULATIONS WERE STOPPED AT  
(N=10000+TOTAL NUMBER OF #STOPS#)\*\*

N= 10080.1000000 PHI = .000021749 LLR= -157.61

LIPOW-SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

\*\*CONVERGENCE WAS NOT REACHED\*\*  
\*\*CALCULATIONS WERE STOPPED AT  
(N=10000+TOTAL NUMBER OF #STOPS#)\*\*

N= 10080.1000000 PHI= .000001664 LLR= -299.87

MODIFIED-LIPOW-SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

N= 140.1000000 PHI= .000012506 LLR= -157.50

MODIFIED GEOMETRIC SOFTWARE RELIABILITY MODEL

D= .1393443 K= .999999998 LLR= -151.51

WEIBULL SOFTWARE RELIABILITY MODEL

ALPHA= 1.2678031 BETA= 5.535613459 LLR= -243.87

THE LIKELIHOOD RATIO TEST HAS SELECTED:  
MODIFIED GEOMETRIC SOFTWARE RELIABILITY MODEL

..

FILE: EF5D

EVALUATION OF GROUP I SOFTWARE RELIABILITY MODELS  
REQUIRING ONLY TIME TO ERROR AS INPUT DATA

TOTAL NUMBER OF ERRORS TO DATE = 170.  
TOTAL NUMBER OF INTERVALS = 83.

PARAMETER ESTIMATIONS FOR THE TESTED MODELS ARE:

JELINSKI-MORANDA SOFTWARE RELIABILITY MODEL

N= 112.0010000 PHI= .004527282 LLR= -182.51

SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

N= 89.0010000 PHI= .002273557 LLR= -208.23

JELINSKI-MORANDA GEOMETRIC SOFTWARE RELIABILITY MODEL

D= .5583315 K= .985014918 LLR= -182.75

WEIBULL SOFTWARE RELIABILITY MODEL

ALPHA= 1.5293342 BETA= 3.509133908 LLR= -204.49

THE LIKELIHOOD RATIO TEST HAS SELECTED:  
JELINSKI-MORANDA SOFTWARE RELIABILITY MODEL



FILE: EF5D

EVALUATION OF GROUP II SOFTWARE RELIABILITY MODELS  
REQUIRING TIME TO ERROR AND NUMBER OF ERRORS PER INTERVAL

TOTAL NUMBER OF ERRORS TO DATE = 170.  
TOTAL NUMBER OF INTERVALS = 83.

PARAMETER ESTIMATIONS FOR THE TESTED MODELS ARE:

LIPOW-JELINSKI-MORANDA SOFTWARE RELIABILITY MODEL

N= 206.1000000 PHI = .005781998 LLR= -210.52

LIPOW-SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

N= 175.1000000 PHI= .002899614 LLR= -403.16

MODIFIED-LIPOW-SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

N= 171.1000000 PHI= .000108849 LLR= -226.90

MODIFIED GEOMETRIC SOFTWARE RELIABILITY MODEL

D= .2803987 K= 1.000000225 LLR= -188.54

WEIBULL SOFTWARE RELIABILITY MODEL

ALPHA= 1.5812815 BETA= 3.512632233 LLR= -394.68

THE LIKELIHOOD RATIO TEST HAS SELECTED:  
MODIFIED GEOMETRIC SOFTWARE RELIABILITY MODEL

..

FILE: EF5E

EVALUATION OF GROUP I SOFTWARE RELIABILITY MODELS  
REQUIRING ONLY TIME TO ERROR AS INPUT DATA

TOTAL NUMBER OF ERRORS TO DATE = 223.  
TOTAL NUMBER OF INTERVALS = 109.

PARAMETER ESTIMATIONS FOR THE TESTED MODELS ARE:

JELINSKI-MORANDA SOFTWARE RELIABILITY MODEL

\*\*CONVERGENCE WAS NOT REACHED\*\*  
\*\*CALCULATIONS WERE STOPPED AT  
(N=10000+TOTAL NUMBER OF #STOPS#)\*\*

N= 10109.0010000 PHI= .000024622 LLR= -261.17

SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

\*\*CONVERGENCE WAS NOT REACHED\*\*  
\*\*CALCULATIONS WERE STOPPED AT  
(N=10000+TOTAL NUMBER OF #STOPS#)\*\*

N= 10109.0010000 PHI= .000002944 LLR= -401.67

JELINSKI-MORANDA GEOMETRIC SOFTWARE RELIABILITY MODEL

D= .1935082 K= 1.004856851 LLR= -259.51

WEIBULL SOFTWARE RELIABILITY MODEL

ALPHA= 1.3986271 BETA= 3.482394209 LLR= -317.98

THE LIKELIHOOD RATIO TEST HAS SELECTED:  
JELINSKI-MORANDA GEOMETRIC SOFTWARE RELIABILITY MODEL

..

FILE: EFSE

EVALUATION OF GROUP II SOFTWARE RELIABILITY MODELS  
REQUIRING TIME TO ERROR AND NUMBER OF ERRORS PER INTERVAL

TOTAL NUMBER OF ERRORS TO DATE = 223.

TOTAL NUMBER OF INTERVALS = 109.

PARAMETER ESTIMATIONS FOR THE TESTED MODELS ARE:

LIPOW-JELINSKI-MORANDA SOFTWARE RELIABILITY MODEL

\*\*CONVERGENCE WAS NOT REACHED\*\*

\*\*CALCULATIONS WERE STOPPED AT

(N=10000+TOTAL NUMBER OF #STOPS#)\*\*

N= 10223.1000000 PHI = .000050097 LLR= -297.24

LIPOW-SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

\*\*CONVERGENCE WAS NOT REACHED\*\*

\*\*CALCULATIONS WERE STOPPED AT

(N=10000+TOTAL NUMBER OF #STOPS#)\*\*

N= 10223.1000000 PHI= .000005970 LLR= -661.09

MODIFIED-LIPOW-SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

N= 248.1000000 PHI= .000023390 LLR= -296.07

MODIFIED GEOMETRIC SOFTWARE RELIABILITY MODEL

D= .2477213 K= 1.000000225 LLR= -261.10

WEIBULL SOFTWARE RELIABILITY MODEL

ALPHA= 1.4959293 BETA= 3.489720447 LLR= -641.54

THE LIKELIHOOD RATIO TEST HAS SELECTED:

MODIFIED GEOMETRIC SOFTWARE RELIABILITY MODEL

\*EOR

..



FILE: EF5F

EVALUATION OF GROUP I SOFTWARE RELIABILITY MODELS  
REQUIRING ONLY TIME TO ERROR AS INPUT DATA

TOTAL NUMBER OF ERRORS TO DATE = 207.  
TOTAL NUMBER OF INTERVALS = 102.

PARAMETER ESTIMATIONS FOR THE TESTED MODELS ARE:

JELINSKI-MORANDA SOFTWARE RELIABILITY MODEL

\*\*CONVERGENCE WAS NOT REACHED\*\*  
\*\*CALCULATIONS WERE STOPPED AT  
(N=10000+TOTAL NUMBER OF #STOPS#)\*\*

N= 10102.0010000 PHI= .000021590 LLR= -257.84

SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

\*\*CONVERGENCE WAS NOT REACHED\*\*  
\*\*CALCULATIONS WERE STOPPED AT  
(N=10000+TOTAL NUMBER OF #STOPS#)\*\*

N= 10102.0010000 PHI= .000003736 LLR= -327.59

JELINSKI-MORANDA GEOMETRIC SOFTWARE RELIABILITY MODEL

D= .2116517 K= 1.000498749 LLR= -257.82

WEIBULL SOFTWARE RELIABILITY MODEL

ALPHA= 1.3914725 BETA= 4.415219075 LLR= -274.46

THE LIKELIHOOD RATIO TEST HAS SELECTED:  
JELINSKI-MORANDA GEOMETRIC SOFTWARE RELIABILITY MODEL

..

FILE: EF5F

EVALUATION OF GROUP II SOFTWARE RELIABILITY MODELS  
REQUIRING TIME TO ERROR AND NUMBER OF ERRORS PER INTERVAL

TOTAL NUMBER OF ERRORS TO DATE = 207.  
TOTAL NUMBER OF INTERVALS = 102.

PARAMETER ESTIMATIONS FOR THE TESTED MODELS ARE:

LIPOW-JELINSKI-MORANDA SOFTWARE RELIABILITY MODEL

N= 425.1000000 PHI = .001412641 LLR= -293.35

LIPOW-SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

N= 925.1000000 PHI= .000093097 LLR= -568.81

MODIFIED-LIPOW-SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

N= 214.1000000 PHI= .000030102 LLR= -298.58

MODIFIED GEOMETRIC SOFTWARE RELIABILITY MODEL

D= .2170157 K= 1.000000225 LLR= -257.83

WEIBULL SOFTWARE RELIABILITY MODEL

ALPHA= 1.5045255 BETA= 4.179165058 LLR= -525.59

THE LIKELIHOOD RATIO TEST HAS SELECTED:

..  
MODIFIED GEOMETRIC SOFTWARE RELIABILITY MODEL  
..

FILE: EF5G

EVALUATION OF GROUP I SOFTWARE RELIABILITY MODELS  
REQUIRING ONLY TIME TO ERROR AS INPUT DATA

TOTAL NUMBER OF ERRORS TO DATE = 198.  
TOTAL NUMBER OF INTERVALS = 80.

PARAMETER ESTIMATIONS FOR THE TESTED MODELS ARE:

JELINSKI-MORANDA SOFTWARE RELIABILITY MODEL

\*\*CONVERGENCE WAS NOT REACHED\*\*  
\*\*CALCULATIONS WERE STOPPED AT  
(N=10000+TOTAL NUMBER OF #STOPS#)\*\*

N= 10080.0010000 PHI= .000010108 LLR= -263.02

SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

\*\*CONVERGENCE WAS NOT REACHED\*\*  
\*\*CALCULATIONS WERE STOPPED AT  
(N=10000+TOTAL NUMBER OF #STOPS#)\*\*

N= 10080.0010000 PHI= .000000691 LLR= -356.08

JELINSKI-MORANDA GEOMETRIC SOFTWARE RELIABILITY MODEL

D= .0808674 K= 1.006034619 LLR= -262.18

WEIBULL SOFTWARE RELIABILITY MODEL

ALPHA= 1.0130925 BETA= 8.081652568 LLR= -265.35

THE LIKELIHOOD RATIO TEST HAS SELECTED:  
JELINSKI-MORANDA GEOMETRIC SOFTWARE RELIABILITY MODEL

..



FILE: EF5G

EVALUATION OF GROUP II SOFTWARE RELIABILITY MODELS  
REQUIRING TIME TO ERROR AND NUMBER OF ERRORS PER INTERVAL

TOTAL NUMBER OF ERRORS TO DATE = 198.  
TOTAL NUMBER OF INTERVALS = 80.

PARAMETER ESTIMATIONS FOR THE TESTED MODELS ARE:

LIPOW-JELINSKI-MORANDA SOFTWARE RELIABILITY MODEL

N= 538.1000000 PHI = .000579303 LLR= -310.98

LIPOW-SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

\*\*CONVERGENCE WAS NOT REACHED\*\*  
\*\*CALCULATIONS WERE STOPPED AT  
(N=10000+TOTAL NUMBER OF #STOPS#)\*\*

N= 10198.1000000 PHI= .000001698 LLR= -599.78

MODIFIED-LIPOW-SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

N= 208.1000000 PHI= .000009344 LLR= -317.00

MODIFIED GEOMETRIC SOFTWARE RELIABILITY MODEL

D= .1015205 K= 1.000000225 LLR= -263.00

WEIBULL SOFTWARE RELIABILITY MODEL

ALPHA= .9783441 BETA= 7.429661570 LLR= -643.07

THE LIKELIHOOD RATIO TEST HAS SELECTED:  
MODIFIED GEOMETRIC SOFTWARE RELIABILITY MODEL

..

FILE: EF5AH

EVALUATION OF GROUP I SOFTWARE RELIABILITY MODELS  
REQUIRING ONLY TIME TO ERROR AS INPUT DATA

TOTAL NUMBER OF ERRORS TO DATE = 432.  
TOTAL NUMBER OF INTERVALS = 131.

PARAMETER ESTIMATIONS FOR THE TESTED MODELS ARE:

JELINSKI-MORANDA SOFTWARE RELIABILITY MODEL

N= 1020.0010000 PHI= .001696781 LLR= -67.87

SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

N= 476.0010000 PHI= .009180697 LLR= -43.09

JELINSKI-MORANDA GEOMETRIC SOFTWARE RELIABILITY MODEL

D= 1.7285712 K= .998994010 LLR= -67.87

WEIBULL SOFTWARE RELIABILITY MODEL

ALPHA= 2.1878506 BETA= .677890384 LLR= -52.64

THE LIKELIHOOD RATIO TEST HAS SELECTED:  
SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

..

FILE: EF5AH

EVALUATION OF GROUP II SOFTWARE RELIABILITY MODELS  
REQUIRING TIME TO ERROR AND NUMBER OF ERRORS PER INTERVAL

TOTAL NUMBER OF ERRORS TO DATE = 432.  
TOTAL NUMBER OF INTERVALS = 131.

PARAMETER ESTIMATIONS FOR THE TESTED MODELS ARE:

LIPOW-JELINSKI-MORANDA SOFTWARE RELIABILITY MODEL

N= 1283.1000000 PHI = .005056635 LLR= -212.86

LIPOW-SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

N= 933.1000000 PHI= .017684491 LLR= -619.92

MODIFIED-LIPOW-SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

N= 463.1000000 PHI= .000807953 LLR= -233.33

MODIFIED GEOMETRIC SOFTWARE RELIABILITY MODEL

D= 1.6178002 K= 1.000000225 LLR= -67.97

WEIBULL SOFTWARE RELIABILITY MODEL

ALPHA= 2.0099102 BETA= .718852616 LLR= -205.50

THE LIKELIHOOD RATIO TEST HAS SELECTED:  
MODIFIED GEOMETRIC SOFTWARE RELIABILITY MODEL

..



FILE: EF5BH

EVALUATION OF GROUP I SOFTWARE RELIABILITY MODELS  
REQUIRING ONLY TIME TO ERROR AS INPUT DATA

TOTAL NUMBER OF ERRORS TO DATE = 292.  
TOTAL NUMBER OF INTERVALS = 130.

PARAMETER ESTIMATIONS FOR THE TESTED MODELS ARE:

JELINSKI-MORANDA SOFTWARE RELIABILITY MODEL

N= 146.0010000 PHI= .026925030 LLR= -45.56

SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

N= 141.0010000 PHI= .025678361 LLR= -258.64

JELINSKI-MORANDA GEOMETRIC SOFTWARE RELIABILITY MODEL

D= 13.1518735 K= .972742772 LLR= -26.77

WEIBULL SOFTWARE RELIABILITY MODEL

ALPHA= .8020556 BETA= .457405985 LLR= -54.28

THE LIKELIHOOD RATIO TEST HAS SELECTED:  
JELINSKI-MORANDA GEOMETRIC SOFTWARE RELIABILITY MODEL

..

FILE: EF5BH

EVALUATION OF GROUP II SOFTWARE RELIABILITY MODELS  
REQUIRING TIME TO ERROR AND NUMBER OF ERRORS PER INTERVAL

TOTAL NUMBER OF ERRORS TO DATE = 292.  
TOTAL NUMBER OF INTERVALS = 130.

PARAMETER ESTIMATIONS FOR THE TESTED MODELS ARE:

LIPOW-JELINSKI-MORANDA SOFTWARE RELIABILITY MODEL

N= 409.2000000 PHI = .015238470 LLR= -110.42

LIPOW-SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

N= 392.2000000 PHI= .013734957 LLR= -620.39

MODIFIED-LIPOW-SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

N= 307.2000000 PHI= .000874744 LLR= -261.64

MODIFIED GEOMETRIC SOFTWARE RELIABILITY MODEL

D= 1.6021067 K= 1.000000225 LLR= -68.72

WEIBULL SOFTWARE RELIABILITY MODEL

ALPHA= .8699890 BETA= .441868617 LLR= -86.38

THE LIKELIHOOD RATIO TEST HAS SELECTED:  
MODIFIED GEOMETRIC SOFTWARE RELIABILITY MODEL

..

FILE: EF5CH

EVALUATION OF GROUP I SOFTWARE RELIABILITY MODELS  
REQUIRING ONLY TIME TO ERROR AS INPUT DATA

TOTAL NUMBER OF ERRORS TO DATE = 80.  
TOTAL NUMBER OF INTERVALS = 49.

PARAMETER ESTIMATIONS FOR THE TESTED MODELS ARE:

JELINSKI-MORANDA SOFTWARE RELIABILITY MODEL

N= 133.0010000 PHI= .008114052 LLR= -55.44

SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

N= 103.0010000 PHI= .010094756 LLR= -77.63

JELINSKI-MORANDA GEOMETRIC SOFTWARE RELIABILITY MODEL

D= 1.2835062 K= .984494710 LLR= -55.15

WEIBULL SOFTWARE RELIABILITY MODEL

ALPHA= 1.1348635 BETA= 1.181769416 LLR= -55.76

THE LIKELIHOOD RATIO TEST HAS SELECTED:  
JELINSKI-MORANDA GEOMETRIC SOFTWARE RELIABILITY MODEL  
..



FILE: EF5CH

EVALUATION OF GROUP II SOFTWARE RELIABILITY MODELS  
REQUIRING TIME TO ERROR AND NUMBER OF ERRORS PER INTERVAL

TOTAL NUMBER OF ERRORS TO DATE = 80.  
TOTAL NUMBER OF INTERVALS = 49.

PARAMETER ESTIMATIONS FOR THE TESTED MODELS ARE:

LIPOW-JELINSKI-MORANDA SOFTWARE RELIABILITY MODEL

N= 127.1000000 PHI = .017387951 LLR= -62.77

LIPOW-SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

N= 111.1000000 PHI= .019708765 LLR= -164.79

MODIFIED-LIPOW-SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

N= 84.1000000 PHI= .001817107 LLR= -93.20

MODIFIED GEOMETRIC SOFTWARE RELIABILITY MODEL

D= .8692568 K= .999999998 LLR= -55.87

WEIBULL SOFTWARE RELIABILITY MODEL

ALPHA= 1.1905967 BETA= 1.101664197 LLR= -91.51

THE LIKELIHOOD RATIO TEST HAS SELECTED:  
MODIFIED GEOMETRIC SOFTWARE RELIABILITY MODEL

..

FILE: EF5DH

EVALUATION OF GROUP I SOFTWARE RELIABILITY MODELS  
REQUIRING ONLY TIME TO ERROR AS INPUT DATA

TOTAL NUMBER OF ERRORS TO DATE = 170.  
TOTAL NUMBER OF INTERVALS = 75.

PARAMETER ESTIMATIONS FOR THE TESTED MODELS ARE:

JELINSKI-MORANDA SOFTWARE RELIABILITY MODEL

N= 104.0010000 PHI= .018365972 LLR= -63.79

SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

N= 80.0010000 PHI= .043824873 LLR= -71.40

JELINSKI-MORANDA GEOMETRIC SOFTWARE RELIABILITY MODEL

D= 2.1701876 K= .983265420 LLR= -63.72

WEIBULL SOFTWARE RELIABILITY MODEL

ALPHA= 1.6347346 BETA= .945031468 LLR= -77.41

THE LIKELIHOOD RATIO TEST HAS SELECTED:  
JELINSKI-MORANDA GEOMETRIC SOFTWARE RELIABILITY MODEL

..

FILE: EF5DH

EVALUATION OF GROUP II SOFTWARE RELIABILITY MODELS  
REQUIRING TIME TO ERROR AND NUMBER OF ERRORS PER INTERVAL

TOTAL NUMBER OF ERRORS TO DATE = 170.  
TOTAL NUMBER OF INTERVALS = 75.

PARAMETER ESTIMATIONS FOR THE TESTED MODELS ARE:

LIPOW-JELINSKI-MORANDA SOFTWARE RELIABILITY MODEL

N= 205.1000000 PHI = .025091666 LLR= -98.18

LIPOW-SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

N= 175.1000000 PHI= .054954685 LLR= -274.08

MODIFIED-LIPOW-SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

N= 171.1000000 PHI= .001963488 LLR= -114.08

MODIFIED GEOMETRIC SOFTWARE RELIABILITY MODEL

D= 1.0872455 K= 1.000000225 LLR= -68.72

WEIBULL SOFTWARE RELIABILITY MODEL

ALPHA= 1.7219281 BETA= .938994089 LLR= -161.96

THE LIKELIHOOD RATIO TEST HAS SELECTED:  
MODIFIED GEOMETRIC SOFTWARE RELIABILITY MODEL

..



FILE: EF5EH

EVALUATION OF GROUP I SOFTWARE RELIABILITY MODELS  
REQUIRING ONLY TIME TO ERROR AS INPUT DATA

TOTAL NUMBER OF ERRORS TO DATE = 223.

TOTAL NUMBER OF INTERVALS = 92.

PARAMETER ESTIMATIONS FOR THE TESTED MODELS ARE:

JELINSKI-MORANDA SOFTWARE RELIABILITY MODEL

N= 136.0010000 PHI= .014357752 LLR= -72.22

SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

N= 118.0010000 PHI= .024763425 LLR= -99.55

JELINSKI-MORANDA GEOMETRIC SOFTWARE RELIABILITY MODEL

D= 2.5625911 K= .984498442 LLR= -70.82

WEIBULL SOFTWARE RELIABILITY MODEL

ALPHA= 1.2124251 BETA= .892276525 LLR= -75.56

THE LIKELIHOOD RATIO TEST HAS SELECTED:  
JELINSKI-MORANDA GEOMETRIC SOFTWARE RELIABILITY MODEL

..

FILE: EF5EH

EVALUATION OF GROUP II SOFTWARE RELIABILITY MODELS  
REQUIRING TIME TO ERROR AND NUMBER OF ERRORS PER INTERVAL

TOTAL NUMBER OF ERRORS TO DATE = 223.  
TOTAL NUMBER OF INTERVALS = 92.

PARAMETER ESTIMATIONS FOR THE TESTED MODELS ARE:

LIPOW-JELINSKI-MORANDA SOFTWARE RELIABILITY MODEL

N= 273.1000000 PHI = .021394947 LLR= -122.05

LIPOW-SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

N= 252.1000000 PHI= .034917187 LLR= -371.89

MODIFIED-LIPOW-SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

N= 227.1000000 PHI= .001293842 LLR= -170.28

MODIFIED GEOMETRIC MODEL

D= 1.1776384 K= 1.000000225 LLR= -76.95

WEIBULL SOFTWARE RELIABILITY MODEL

ALPHA= 1.2576628 BETA= .867753088 LLR= -174.28

THE LIKELIHOOD RATIO TEST HAS SELECTED:  
MODIFIED GEOMETRIC MODEL

..

FILE: EF5FH

EVALUATION OF GROUP I SOFTWARE RELIABILITY MODELS  
REQUIRING ONLY TIME TO ERROR AS INPUT DATA

TOTAL NUMBER OF ERRORS TO DATE = 207.

TOTAL NUMBER OF INTERVALS = 90.

PARAMETER ESTIMATIONS FOR THE TESTED MODELS ARE:

JELINSKI-MORANDA SOFTWARE RELIABILITY MODEL

N= 106.0010000 PHI= .023368186 LLR= -67.17

SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

N= 103.0010000 PHI= .022910804 LLR= -157.92

JELINSKI-MORANDA GEOMETRIC SOFTWARE RELIABILITY MODEL

D= 6.9393877 K= .965056505 LLR= -58.10

WEIBULL SOFTWARE RELIABILITY MODEL

ALPHA= .8551609 BETA= .779779826 LLR= -76.41

THE LIKELIHOOD RATIO TEST HAS SELECTED:

JELINSKI-MORANDA GEOMETRIC SOFTWARE RELIABILITY MODEL

..



FILE: EF5FH

EVALUATION OF GROUP II SOFTWARE RELIABILITY MODELS  
REQUIRING TIME TO ERROR AND NUMBER OF ERRORS PER INTERVAL

TOTAL NUMBER OF ERRORS TO DATE = 207.  
TOTAL NUMBER OF INTERVALS = 90.

PARAMETER ESTIMATIONS FOR THE TESTED MODELS ARE:

LIPOW-JELINSKI-MORANDA SOFTWARE RELIABILITY MODEL

N= 218.1000000 PHI = .036308260 LLR= -109.78

LIPOW-SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

N= 215.1000000 PHI= .035881426 LLR= -406.03

MODIFIED-LIPOW-SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

N= 207.1000000 PHI= .001809664 LLR= -198.62

MODIFIED GEOMETRIC SOFTWARE RELIABILITY MODEL

D= 1.1246817 K= 1.000000225 LLR= -79.42

WEIBULL SOFTWARE RELIABILITY MODEL

ALPHA= .8218078 BETA= .657791428 LLR= -144.34

THE LIKELIHOOD RATIO TEST HAS SELECTED:  
MODIFIED GEOMETRIC SOFTWARE RELIABILITY MODEL

..

FILE: EF5GH

EVALUATION OF GROUP I SOFTWARE RELIABILITY MODELS  
REQUIRING ONLY TIME TO ERROR AS INPUT DATA

TOTAL NUMBER OF ERRORS TO DATE = 198.  
TOTAL NUMBER OF INTERVALS = 76.

PARAMETER ESTIMATIONS FOR THE TESTED MODELS ARE:

JELINSKI-MORANDA SOFTWARE RELIABILITY MODEL

N= 78.0010000 PHI= .044198370 LLR= -48.82

SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

N= 76.0010000 PHI= .028922954 LLR= -196.67

JELINSKI-MORANDA GEOMETRIC SOFTWARE RELIABILITY MODEL

D= 14.4139897 K= .945673555 LLR= -32.41

WEIBULL SOFTWARE RELIABILITY MODEL

ALPHA= .6378079 BETA= .599887132 LLR= -54.62

THE LIKELIHOOD RATIO TEST HAS SELECTED:

.JELINSKI-MORANDA GEOMETRIC SOFTWARE RELIABILITY MODEL

..

FILE: EF5GH

EVALUATION OF GROUP II SOFTWARE RELIABILITY MODELS  
REQUIRING TIME TO ERROR AND NUMBER OF ERRORS PER INTERVAL

TOTAL NUMBER OF ERRORS TO DATE = 198.  
TOTAL NUMBER OF INTERVALS = 76.

PARAMETER ESTIMATIONS FOR THE TESTED MODELS ARE:

LIPOW-JELINSKI-MORANDA SOFTWARE RELIABILITY MODEL

N= 198.1000000 PHI = .068513675 LLR= -91.83

LIPOW-SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

N= 198.1000000 PHI= .044056958 LLR= -431.00

MODIFIED-LIPOW-SCHICK-WOLVERTON SOFTWARE RELIABILITY MODEL

N= 198.1000000 PHI= .002860647 LLR= -185.42

MODIFIED GEOMETRIC SOFTWARE RELIABILITY MODEL

D= .9447691 K= 1.000000225 LLR= -80.32

WEIBULL SOFTWARE RELIABILITY MODEL

ALPHA= .6623245 BETA= .391920693 LLR= -62.85

THE LIKELIHOOD RATIO TEST HAS SELECTED:  
WEIBULL SOFTWARE RELIABILITY MODEL



## Appendix D

### Program Time-To-Fix Input

Contained within this appendix is a portion of File5 used as input into Program Time-To-Fix, which was used to select a distribution for the software time-to-fix data files. The first six positions are the time it took to fix the software error. The seventh position is the criticality of the error and the last five positions indicate the error category which was deemed appropriate for this particular software problem report.

Input-for Program Time-To-Fix

.84DBB060  
.84DBB060  
.84CBB070  
.84DBB080  
.84CBB060  
.85CBB020  
.86DBB130  
.86CBB070  
.87DBB070  
.87CBB070  
.88DBB140  
.88DBB120  
.88DBB060  
.88UBB070  
.88CBB060  
.88CBB140  
.88CBB070  
.90CBB070  
.90CBB060  
.90CBB070  
.91DBB080  
.92CBB080  
.92CBB070  
.92CBB070  
.92CBB070  
.93DBB060  
.93DBB060  
.93CBB070  
.93DBB060  
.93CBB140  
.94DBB060  
.94DBB080  
.95CBB080  
.95CBB140  
.95CBB070  
.95DBB140  
.95CBB060  
.95DBB070  
.95CBB070  
.97CBB070  
.97DBB070  
.99DBB140  
.99DBB140

## Appendix E

### Program Time-To-Fix's Output

The next three pages are typical outputs from Program Time-To-Fix. The first is the result of using file FF3 as input without regards to error categories. The second page is the output for category "KK" of file FF5. As can be seen the log-normal distribution was selected. Finally, the third listing shows what happened when there was only one data point entered as data.



INPUT CONSISTED OF 219 POINTS

PART I. PARAMETER ESTIMATION

DISTRIBUTION	PARAMETER 1	PARAMETER 2
UNIFORM	ALPHA = .5000E+00	BETA = .4800E+02
EXPONENTIAL	THETA = .5000E+01	MU = .5244E+01
WEIBULL	BETA = .1080E+01	ALPHA = .5244E+01
NORMAL	MU = .5744E+01	SIGMA = .7139E+01
LOG-NORMAL	MU = .1123E+01	SIGMA = .1133E+01
GAMMA	ALPHA = .9407E+01	BETA = .6105E+01
LOGISTIC	MU = .5744E+01	SIGMA = .7139E+01
EXT VALUE-SMALLEST	BETA = .5566E+01	MU = .8957E+01
EXT VALUE-LARGEST	BETA = .5566E+01	MU = .2532E+01
PARETO	K = .5000E+00	A = .5508E+00
LAPLACE	THETA = .4300E+01	PHI = .1744E+01

PART II. KOLMOGOROV-SMIRNOV TEST (MAX DVALUE = .07233)

DISTRIBUTION	MAX KSVALUE	DECISION
UNIFORM	.65922	REJECT
EXPONENTIAL	.21500	REJECT
WEIBULL	.15207	REJECT
NORMAL	.22471	REJECT
LOG-NORMAL	.13762	REJECT
GAMMA	.13327	REJECT
LOGISTIC	.20418	REJECT
EXT VALUE-SMALLEST	.25739	REJECT
EXT VALUE-LARGEST	.23224	REJECT
PARETO	.23475	REJECT
LAPLACE	.22927	REJECT

PART III. LIKELIHOOD RATIO TEST.

DISTRIBUTION	LN OF LIKELIHOOD FUNCTION
UNIFORM	-345.
EXPONENTIAL	-582.
WEIBULL	-683.
NORMAL	-741.
LOG-NORMAL	-594.
GAMMA	-501.
LOGISTIC	-738.
EXT VALUE-SMALLEST	999939.
EXT VALUE-LARGEST	-531.
PARETO	-595.
LAPLACE	-418.

PART IV. DECISION.

NO DISTRIBUTION WAS SELECTED.

ANALYSIS OF CATEGORY 'KK'  
INPUT CONSISTED OF 31 POINTS

PART I. PARAMETER ESTIMATION

DISTRIBUTION	PARAMETER 1	PARAMETER 2
UNIFORM	ALPHA = .1000E+01	BETA = .8900E+02
EXPONENTIAL	THETA = .1300E+01	MU = .1329E+02
WEIBULL	BETA = .9425E+00	ALPHA = .7997E+01
NORMAL	MU = .1129E+02	SIGMA = .1837E+02
LOG-NORMAL	MU = .1467E+01	SIGMA = .1351E+01
GAMMA	ALPHA = .6352E+00	BETA = .1727E+02
LOGISTIC	MU = .1129E+02	SIGMA = .1937E+02
EXT VALUE-SMALLEST	BETA = .1432E+02	MU = .1956E+02
EXT VALUE-LARGEST	BETA = .1432E+02	MU = .3023E+01
PARETO	K = .1000E+01	A = .6818E+00
LAPLACE	THETA = .3000E+01	PHI = .8290E+01

PART II. KOLMOGOROV-SMIRNOV TEST (MAX DVALUE = .19218)

DISTRIBUTION	MAX KSVALUE	DECISION
UNIFORM	.65925	REJECT
EXPONENTIAL	.35901	REJECT
WEIBULL	.21435	REJECT
NORMAL	.29155	REJECT
LOG-NORMAL	.16674	ACCEPT
GAMMA	.19290	REJECT
LOGISTIC	.29823	REJECT
EXT VALUE-SMALLEST	.36165	REJECT
EXT VALUE-LARGEST	.28383	REJECT
PARETO	.29032	REJECT
LAPLACE	.36057	REJECT

PART III. LIKELIHOOD RATIO TEST.

DISTRIBUTION	LN OF LIKELIHOOD FUNCTION
UNIFORM	-138.
EXPONENTIAL	-103.
WEIBULL	-106.
NORMAL	-134.
LOG-NORMAL	-99.
GAMMA	-104.
LOGISTIC	-130.
EXT VALUE-SMALLEST	999999.
EXT VALUE-LARGEST	-125.
PARETO	-88.
LAPLACE	-124.

PART IV. DECISION.

THE LIKELIHOOD RATIO AND KOLMOGOROV-SMIRNOV TESTS HAVE SELECTED THE LOG-NORMAL DISTRIBUTION. PARAMETERS ARE  
MU = .1467E+01 SIGMA = .1351E+01

ANALYSIS OF CATEGORY 'AA100'  
INPUT CONSISTED OF 1 POINTS  
NOT ENOUGH DATA POINTS FOR FURTHER ANALYSIS



Appendix F

Software Error Categories

This appendix contains a listing of the software error categories used by the contractors during error collection procedures (Ref [3017]:45-50).

# ERROR CATEGORIES

CATEGORY ID	CATEGORIES
AA000	COMPUTATIONAL ERRORS
AA010	TOTAL NUMBER OF ENTRIES COMPUTED INCORRECTLY
AA020	PHYSICAL OR LOGICAL ENTRY NUMBER COMPUTED INCORRECTLY
AA040	WRONG EQUATION OR CONVENTION USED
AA041	MATHEMATICAL MODELING PROBLEM
AA050	RESULTS OF ARITHMETIC CALCULATION INACCURATE/NOT AS EXPECTED
AA060	MIXED MODE ARITHMETIC ERROR
AA070	TIME CALCULATION ERROR
AA071	TIME CONVERSION ERROR
AA072	TIME TRUNCATION/ROUNDING ERROR
AA080	SIGN CONVENTION ERROR
AA090	UNITS CONVERSION ERROR
AA100	VECTOR CALCULATION ERROR
AA110	CALCULATION FAILS TO CONVERGE
AA120	QUANTIZATION/TRUNCATION ERROR
BB000	LOGIC ERRORS
BB010	LIMIT DETERMINATION ERROR
BB020	WRONG LOGIC BRANCH TAKEN
BB030	LOOP EXITED ON WRONG CYCLE
BB040	INCOMPLETE PROCESSING
BB050	ENDLESS LOOP DURING ROUTINE OPERATION
BB060	MISSING LOGIC OR CONDITION TEST
BB061	INDEX NOT CHECKED
BB062	FLAG OR SPECIFIC DATA VALUE NOT TESTED
BB070	INCORRECT LOGIC
BB080	SEQUENCE OF ACTIVITIES WRONG
BB090	FILTERING ERROR
BB100	STATUS CHECK/PROPAGATION ERROR
BB110	ITERATION STEP SIZE INCORRECTLY DETERMINED
BB120	LOGICAL CODE PRODUCED WRONG RESULTS
BB130	LOGIC ON WRONG ROUTINE
BB140	PHYSICAL CHARACTERISTICS OF PROBLEM TO BE SOLVED, OVERLOOKED, OR MISUNDERSTOOD
BB150	LOGIC NEEDLESSLY COMPLEX
BB160	INEFFICIENT LOGIC
BB170	EXCESSIVE LOGIC
BB180	STORAGE REFERENCE ERROR (SOFTWARE PROBLEM)

# ERROR CATEGORIES

CATEGORY ID	CATEGORIES
CC000	I/O ERRORS
CC010	MISSING OUTPUT
CC020	OUTPUT MISSING DATA ENTRIES
CC030	ERROR MESSAGE NOT OUTPUT
CC040	ERROR MESSAGE GARBLED
CC050	OUTPUT OR ERROR MESSAGE NOT COMPATIBLE WITH DESIGN DOCUMENTATION (INCLUDING GARBLED OUTPUT)
CC060	MISLEADING OR INACCURATE ERROR MESSAGE TEXT
CC070	OUTPUT FORMAT ERROR (INCLUDING WRONG LOCATION)
CC080	DUPLICATE OR EXCESSIVE OUTPUT
CC090	OUTPUT FIELD SIZE INADEQUATE
CC100	DEBUG OUTPUT PROBLEM (RELATIVE TO DESIGN DOCUMENTATION)
CC101	LACK OF DEBUG OUTPUT
CC102	TOO MUCH DEBUG
CC110	HEADER OUTPUT PROBLEM
CC120	OUTPUT TAPE FORMAT ERROR
CC130	OUTPUT CARD FORMAT ERROR
CC140	ERROR IN PRINTER CONTROL
CC150	LINE COUNT/PAGE EJECT ERROR
CC160	NEEDED OUTPUT NOT PROVIDED IN DESIGN
CC161	INSUFFICIENT OUTPUT OPTIONS
DD000	DATA HANDLING ERRORS
DD010	VALID INPUT DATA IMPROPERLY SET/USED
DD020	DATA WRITTEN IN OR READ FROM WRONG DISK LOCATION
DD030	DATA LOST/NOT STORED
DD040	DATA, INDEX OR FLAG NOT SET OR SET/INITIALIZED INCORRECTLY
DD041	NUMBER OF ENTRIES SET INCORRECTLY
DD050	DATA, INDEX OR FLAG MODIFIED OR UPDATED INCORRECTLY
DD051	NUMBER OF ENTRIES UPDATED INCORRECTLY
DD060	EXTRANEIOUS ENTRIES GENERATED (TABLE, ARRAY, ETC.)
DD070	BIT MANIPULATION ERROR
DD071	ERROR USING BIT MODIFIER
DD080	FLOATING POINT/INTEGER CONVERSION ERROR
DD090	INTERNAL VARIABLE ERROR (DEFINITION OR SET/USE)
DD100	DATA PACKING/UNPACKING ERROR
DD110	ROUTINE LOOKING FOR DATA IN NON-EXISTENT RECORD
DD120	BOUNDS VIOLATION
DD130	DATA CHAINING ERROR
DD140	DATA OVERLOW OR OVERFLOW PROCESSING ERROR
DD150	READ ERROR
DD151	ALL AVAILABLE DATA NOT READ
DD160	LONG LITERAL PROCESSING ERROR
DD170	SORT ERROR
DD180	OVERLAY ERROR
DD190	SUBSCRIPTING CONVENTION ERROR
DD200	DOUBLE BUFFERING ERROR



# ERROR CATEGORIES

CATEGORY ID	CATEGORIES
EE000 EE010 EE020	OPERATING SYSTEM/SYSTEM SUPPORT SOFTWARE ERRORS JOVIAL PRODUCES ERRONEOUS MACHINE CODE OS MISSING NEEDED CAPABILITY
FF000 FF010 FF011 FF020 FF030	CONFIGURATION ERRORS COMPILATION ERROR SEGMENTATION PROBLEM ILLEGAL INSTRUCTION UNEXPLAINABLE PROGRAM HALT
GG000 GG010  GG020 GG030 GG040 GG050 GG060 GG070 GG080 GG090 GG100	ROUTINE/ROUTINE INTERFACE ERRORS ROUTINE PASSING INCORRECT AMOUNT OF DATA (INSUFFICIENT OR TOO MUCH) ROUTINE PASSING WRONG PARAMETERS OR UNITS ROUTINE EXPECTING WRONG PARAMETERS ROUTINE FAILS TO USE AVAILABLE DATA ROUTINE SENSITIVE TO INPUT DATA ORDER CALLING SEQUENCE OR ROUTINE/ROUTINE INITIALIZATION ERROR ROUTINES COMMUNICATING THROUGH WRONG DATA BLOCK ROUTINE USED OUTSIDE DESIGN LIMITATION ROUTINE WON'T LOAD (ROUTINE INCOMPATIBILITY) ROUTINE OVERFLOWS CORE WHEN LOADED
HH000 HH010 HH020 HH030	ROUTINE/SYSTEM SOFTWARE INTERFACE ERRORS OS INTERFACE ERROR (CALLING SEQUENCE OR INIALIZATION) ROUTINE USES EXISTING SYSTEM SUPPORT SOFTWARE INCORRECTLY ROUTINE USES SENSE/JUMP SWITCH IMPROPERLY
II000 II010 II020 II030 II040	TAPE PROCESSING INTERFACE ERROR TAPE UNIT EQUIPMENT CHECK NOT MADE ROUTINE FAILS TO READ CONTINUATION TAPE ROUTINE FAILS TO UNLOAD TAPE AFTER COMPLETION ERRONEOUS INPUT TAPE FORMAT

# ERROR CATEGORIES

CATEGORY ID	CATEGORIES
JJ000 JJ010 JJ020 JJ030 JJ040 JJ050 JJ060 JJ070 JJ080 JJ090 JJ100	USER INTERFACE ERRORS OPERATIONS REQUEST OR DATA CARD/ROUTINE INCOMPATABILITY MULTIPLE PHYSICAL CARD/LOGICAL CARD PROCESSING ERROR INPUT DATA INTERPRETED INCORRECTLY BY ROUTINE VALID INPUT DATA REJECTED OR NOT USED BY ROUTINE INPUT DATA REJECTED BUT USED INPUT DATA READ BUT NOT USED ILLEGAL INPUT DATA ACCEPTED AND PROCESSED LEGAL INPUT DATA PROCESSED INCORRECTLY POOR DESIGN IN OPERATOR INTERFACE INADEQUATE INTERRUPT AND START CAPABILITY
KK000 KK010 KK011	DATA BASE INTERFACE ERRORS ROUTINE/DATA BASE INCOMPATIBILITY UNCOORDINATED USE OF DATA ELEMENTS BY MORE THAN ONE USER
LL000 LL010 LL020 LL021 LL022 LL023 LL024 LL025 LL030 LL040 LL050 LL060 LL070 LL080	USER REQUESTED CHANGES SIMPLIFIED INTERFACE AND/OR CONVENIENCE NEW AND/OR ENHANCED FUNCTIONS CPU DISK TAPE I/O CORE SECURITY NEW HARDWARE/OS CAPABILITY INSTRUMENTATION CAPACITY DATA BASE MANAGEMENT AND INTEGRITY EXTERNAL PROGRAM INTERFACE
MM000 MM010 MM020 MM030 MM040 MM041 MM050 MM060	PRESET DATA BASE ERRORS DATA OR OPERATIONS REQUEST CARD DESCRIPTIONS ERROR MESSAGE TEXT NOMINAL, DEFAULT, LEGAL, MAX/MIN VALUES PHYSICAL CONSTANTS AND MODELING PARAMETERS EPHEMERIS PARAMETERS DICTIONARY (BIT STRING) PARAMETERS MISSING DATA BASE SETTINGS

# ERROR CATEGORIES

CATEGORY ID	CATEGORIES
NN000 NN010 NN011 NN020 NN021 NN030 NN040 NN050	GLOBAL VARIABLE/COMPOOL DEFINITION ERRORS ITEMS IN WRONG LOCATION (WRONG DATA BLOCK) DEFINITION SEQUENCE ERROR DATA DEFINITION ERROR TABLE DEFINITION INCORRECT LENGTH OF DEFINITION INCORRECT COMMENTS ERROR DELETE UNNEEDED DEFINITIONS
PP000 PP010 PP020	RECURRENT ERRORS PROBLEM REPORT REOPENED PROBLEM REPORT A DUPLICATE OF PREVIOUS REPORT
QQ000 QQ010 QQ020 QQ030 QQ040 QQ050 QQ060 QQ070 QQ080 QQ090 QQ100 QQ110 QQ120	DOCUMENTATION ERRORS ROUTINE LIMITATION OPERATING PROCEDURES DIFFERENCE BETWEEN FLOW CHART AND CODE TAPE FORMAT DATA CARD/OPERATION REQUEST CARD FORMAT ERROR MESSAGE ROUTINE'S FUNCTIONAL DESCRIPTION OUTPUT FORMAT DOCUMENTATION NOT CLEAR/NOT COMPLETE TEST CASE DOCUMENTATION OPERATING SYSTEM DOCUMENTATION TYPO/EDITORIAL ERROR/COSMETIC CHANGE
RR000 RR010 RR020	REQUIREMENTS COMPLIANCE ERRORS EXCESSIVE RUN TIME REQUIRED CAPABILITY OVERLOOKED OR NOT DELIVERED AT TIME OF REPORT



# ERROR CATEGORIES

CATEGORY ID	CATEGORIES
SS000	UNIDENTIFIED ERRORS
TT000 TT010 TT020 TT030 TT040 TT050	OPERATOR ERROR TEST EXECUTION ERROR ROUTINE COMPILED AGAINST WRONG COMPOOL/MASTER COMMON WRONG DATA BASE USED WRONG MASTER CONFIGURATION USED WRONG TAPE(S) USED
UU000 UU010 UU020 UU030	QUESTIONS DATA BASE MASTER CONFIGURATION ROUTINE
V	HARDWARE
X	NON-REPRODUCIBLE

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## Vita

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governing the random variable time-to-fix. Time-to-fix data was extracted from data base and was sorted by error categories. Eleven of the more common probability density functions, along with the Kolmogorov-Smirnov Test and the Likelihood Ratio Test, were used to isolate the distribution that best modelled software time-to-fix for each particular data set.

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